

Grammatical Acquisition: Coevolution of Language and the Language Acquisition Device

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October 27, 1998

Abstract

An account of grammatical acquisition is developed within the parameter-setting framework applied to a generalized categorial grammar (GCG). The GCG is embedded in a default inheritance network yielding a natural partial ordering (reflecting generality) of parameters which determines a partial order for parameter setting. Computational simulation shows that several resulting acquisition procedures are effective on a grammar / language set expressing major typological distinctions based on constituent order, and defining 70 distinct full languages and over 200 subset languages. The effects on acquisition of maturational working memory limitations, trigger presentation sequences, parameter update criteria, and differing initial settings are explored via computational simulation.

Computational simulations of populations of language learners / users instantiating the model show: 1) that variant acquisition procedures with differing constraints and biases exert differing selective pressures on the evolution of language; 2) acquisition procedures will evolve towards more efficient variants in the environment of adaptation. The reciprocal evolution of language acquisition procedures and of language creates a genuinely coevolutionary dynamic, despite the relative speed of linguistic selection for language variants compared to natural selection for variant language acquisition procedures.¹

¹I would like to thank seminar audiences at the Universities of Edinburgh, Sussex and Cambridge, and Oregon Graduate Institute, as well as the organizers and participants of the 1st and 2nd International Conferences. on Language and Evolution, University of Edinburgh, 1996, and University of East London, 1998, for helpful feedback on aspects of the work described in this paper. In particular, Bob Berwick, Miriam Eckert and Jim Hurford made suggestions which influenced the subsequent development and presentation of this work. In addition, Ann Copestake, Gerald Gazdar, Hans van Halteren, Simon Kirby, David Lightfoot, David Milward, Geoff Pullum and two anonymous reviewers for *Language* kindly gave comments on earlier drafts which helped considerably improve the present one.

1 Theoretical Background

It is widely accepted that language acquisition is guided by an innate language acquisition procedure and a partial innate specification of the form of language. Language acquisition by children is a near-universal feat, where (partial) failure appears to correlate more with genetic deficits (e.g. Gopnik, 1994) or with an almost complete lack of linguistic input during the critical period (e.g. Curtiss, 1988), than with measures of general intelligence (e.g. Smith and Tsimpli, 1991) or the quality or informativeness of the learning environment (e.g. Bickerton, 1981; Kegl and Iwata, 1989; Ochs and Sheffelin, 1995).² There is considerable psycholinguistic evidence that children have strong biases in language acquisition which shape their linguistic development, the nature of their errors, and the kind of languages they are predisposed to learn. Often these biases are partially incorrect as generalizations about the nature of human languages. For example, Wanner and Gleitman (1982:12f) argue that children are predisposed to learn lexical compositional systems in which atomic elements of meaning are mapped to individual words. This leads to errors where languages, for example, mark negation morphologically. Similarly, Clark (1993) argues for a principle of contrast in lexical acquisition, suggesting that children hypothesize novel meanings for novel words, ignoring, at least initially, the hypothesis that a new word may be synonymous with a known one. How do sometimes inaccurate biases of this kind arise and how pervasive are they in language acquisition?

1.1 Grammatical Acquisition

Grammatical acquisition proceeds on the basis of a partial genotypic specification of (universal) grammar (UG) complemented with a learning procedure enabling the child to complete this specification appropriately on exposure to finite positive samples from a given language. The parameter setting framework of Chomsky (1981) claims that learning involves fixing the values of a finite set of finite-valued parameters to select a single fully-specified grammar from within the space defined by the genotypic specification of UG. Formal models of parameter setting have been developed for small fragments, but even the search spaces defined by these models contain local maxima and subset-superset relations which may cause a learner to converge to an incorrect grammar (Clark, 1992; Gibson and Wexler, 1994; Niyogi and Berwick, 1996; Wexler and Manzini, 1987).

Gibson and Wexler (1994) formalize the concept of a trigger (e.g. Lightfoot, 1992:13f) as a simple (unembedded or degree-0) sentence of primary linguistic data which signals the value of some parameter and can serve to guide the learner to the target grammar. The notion of a trigger is a refinement of that of primary linguistic data, which, through context of use, unambiguously signals a particular surface form (SF) to logical form (LF) pairing (e.g. Wexler and Culicover, 1980). Thus the task of the learner faced with a trigger, or SF-LF pairing, not expressible given the current grammar, is to update a parameter such that the trigger can be parsed appropriately. Frank and Kapur (1996) demonstrate that the existence of locking sequences of such triggers, guaranteeing convergence to a target grammar, depends on the nature of the parameters, on the specific acquisition procedure, and on the starting point for learning.

Chomsky (1981:7f) argued that at least some parameters probably have an initially unmarked or default value which will be retained by the learner unless incompatible with input. That is, that the learner is biased towards certain settings of some parameters. Unmarked, default values have been proposed as a mechanism

²See, e.g., Pinker (1994) or Aitchison (1996) for recent positive summaries and discussion of this evidence. See Sampson (1989) for a dissenting view.

for avoiding premature acquisition of a superset grammar (Hyams, 1986; Wexler and Manzini, 1987; Lightfoot, 1992). However, formal work on parameter setting has tended to assume arbitrary initial configurations of parameters in evaluating learnability, perhaps because initial unmarked settings have only been proposed and justified for a few putative parameters. In addition, there have been no proposals concerning the grammatical representation and formalization of the distinction between initially unset and initially default parameters. Chomsky (1981:8) also proposed that the same mechanism might well be responsible for acquisition of the periphery of marked idiosyncratic constructions for which positive evidence was provided by a given language community. However, there has been little attempt to provide a formal model of grammatical representation and acquisition capable of incorporating these insights.

Pullum (1983) criticizes the parameter setting framework because it predicts that the space of possible grammars, and thus languages, is vast, though finite (20 independent binary parameters yields 2^{20} or 1,048,576 grammars, whilst 30 such parameters yields 1,073,741,824 distinct grammars), and because few if any psychologically feasible, as opposed to merely computationally tractable, acquisition procedures have been proposed within this framework. For example, brute force search through the space of distinct grammars will require time proportional to their number (e.g. Clark, 1992), whilst the number of positive samples of the language and hence amount of time required for convergence to a target grammar can be arbitrarily long depending on the distribution of trigger types in the language (e.g. Niyogi and Berwick, 1996).

The model presented in section 2 addresses these issues via a modified parameter setting procedure, which can learn more complex grammars than those investigated by Gibson and Wexler, and which is more directed and therefore less psychologically implausible than the Markovian ‘memoryless’ procedures of the type investigated by Niyogi and Berwick (e.g. Brent, 1996). The modified procedure is based on a partial ordering on the updating of parameter settings, defining the category set and rule schemata available in a categorial grammar. The partial ordering is obtained by use of a default inheritance network as the grammatical representation language. The generalized categorial grammar (GCG) framework supports a more articulated account of UG than is typically deployed in recent formal work on parameter setting, enabling a wider space of grammars to be explored, and a richer notion of parameter updating to emerge. Parameters are set in (partial) order of their generality in defining the space of possible grammatical categories, ensuring that grammatical hypotheses remain maximally specific, though further modifiable due to the defeasibility of their consequences. The grammatical representation language provides a formal means for distinguishing unset, default and absolute specification, and thus for distinguishing unset or (un)marked parameters from principles. Variants of this acquisition procedure can be defined based on the criterion adopted for retaining a new parameter setting, on the number of new parameter settings per trigger, on the existence of (maturational) working memory limits during learning, and on the initial configuration of the parameter set.

For Gibson and Wexler (1994), following Wexler and Culicover (1980), the criterion for retaining a new parameter setting is successful recovery of a complete and contextually-appropriate LF for the input; for Dresher and Kaye (1990), it is recognition of an unambiguous structural cue for that new setting. The cue-based approach to parameter setting of Dresher and Kaye results in a more incremental acquisition procedure which can be less sensitive to trigger presentation order. On the other hand, allowing more than one parameter per trigger sentence to be updated may counteract this sensitivity without changing fundamental properties of the acquisition procedure (Bertolo, 1995). In addition, as the relationship between parameters and a specific account of UG becomes more articulated, the complete

independence of parameters becomes increasingly questionable (e.g. Dresher and Kaye, 1990) and consequently it is difficult to maintain both recovery of a full LF as the success criterion and the restriction to updating a single parameter per trigger. Some of the consequences of such variants within the parameter setting framework are explored experimentally in section 4.

Elman (1993) argues, following Newport (1990), that language learning ‘starts small’, restricted by working memory limitations which block the learner from seeing complex triggering data until later in the learning process. It is known that working memory capacity increases through childhood (e.g. Baddeley, 1976, 1992) and that this correlates with language comprehension ability (e.g. King and Just, 1991; Gathercole and Baddeley, 1993). A maturing working memory may serve as a filter on trigger input and ‘internally’ impose an order on the complexity of triggering data and thus on parameter setting. The language acquisition device (LAD) must incorporate a UG, a parameter setting procedure, and a parser capable of applying the current grammar to primary linguistic data (e.g. Berwick, 1985). The parser will require a working memory to store (sub)analyses and the amount of memory required will vary for different constructions (and grammars). Restrictions on the working memory resources available to the parser can be used to distinguish parse failure due to an incorrect grammar from parse failure due to overloading of working memory. The empirical consequences of internal filtering for a class of parameter setting learners is explored experimentally in sections 4.1 and 6.

The starting point for a parameter setting procedure is defined by the initial unset state or default setting of each parameter. The framework developed here is capable of expressing any such start state within the grammatical space explored. The learnability of each grammar may be affected by this starting point (e.g. Gibson and Wexler, 1994), but linguists have often argued for default initial values for specific parameters. Bickerton (1984), in particular, argues that the abrupt transition from pidgin to creole suggests that children are endowed genetically with initial parameter settings specifying the stereotypical core creole grammar. The consequences of several starting points for the acquisition procedure are explored experimentally in sections 4.1 and 7, and it is argued on evolutionary grounds that the LAD is probably equipped with a highly-informative and largely accurate starting point for acquisition with respect to the languages sampled during the period of adaptation. That is, many parameters will have default, unmarked values appropriate to (some of) these ancestral languages.

1.2 Linguistic Evolution

The use of evolutionary terms and ideas in linguistic theory is not new³ but, advances in the understanding of dynamic systems and the availability of computational simulation techniques now make it possible to move beyond loose use of terminology, primarily as a metaphor, and study language directly from an evolutionary perspective. There are two ways in which evolutionary theory might bear on language. Firstly, it is possible, indeed highly probable, that the LAD is adaptive and has been selected for via biological evolution in the hominid line (e.g. Pinker and Bloom, 1990; Newmeyer, 1991, 1992). But secondly, language *itself* can be viewed as a dynamic system which adapts to its niche – of human language learners and users (e.g. Cziko, 1995; Hurford, 1987; 1998; Keller, 1994). In this second view,

³Müller, Schleicher and other 19th century linguists speculated that languages evolved according to Darwinian theory, and Darwin (1871) endorsed the idea, quoting with approval from Müller: ‘A struggle for life is constantly going on amongst the words and grammatical forms in each language. The better, the shorter, the easier forms are constantly gaining the upper hand, and they owe their success to their own inherent virtue.’ See Harris and Taylor (1997:ch14) and McMahon (1994:ch12) for more discussion of the relationship between Darwinian and linguistic theory, and Keller (1994:46f) for a critical discussion of Müller and Schleicher’s theories of language.

it is language which is evolving on a historical timescale, and the primary source of *linguistic* selection is the language acquisition ‘bottleneck’ through which successful grammatical forms must pass repeatedly with each generation of new language learners.

Under this second view, the concepts of linguistic evolution and selection are being used in their technical ‘universal Darwinist’ sense of (random) variation, adaptive selection and differential inheritance applied to any dynamic system (e.g. Dawkins, 1983; Cziko, 1995). To study linguistic evolution, it is necessary to move from the study of individual (idealized) language learners and users, endowed with a LAD and acquiring an idiolect, to the study of *populations* of such generative language learners and users, parsing, learning and generating a set of idiolects constituting the language of a community. Once this step is taken, then the dynamic nature of language emerges more or less inevitably. Occasional misconvergences on the part of language users can introduce variation into a previously homogeneous linguistic environment, fluctuations in the proportion of learners to adults in the population can skew the distribution of primary linguistic data significantly enough to affect grammatical acquisition, and so forth. Once such variation is introduced, then properties of the acquisition procedure become critical in determining which grammatical forms will be differentially selected for and maintained in the language, with language acquisition across the generations of users as the primary form of linguistic inheritance.

Several researchers have recently proposed that language can be treated as a dynamic or (complex) adaptive system in order to formally model aspects of language change (e.g. Niyogi and Berwick, 1997a,b) or account for typological, statistical and implicational universals (e.g. Kirby, 1996, 1997, 1998). In generative work on diachronic syntax, language change is primarily located in parameter resetting (reanalysis) during language acquisition (e.g. Lightfoot, 1979, 1992, 1997; Clark and Roberts, 1993; Kroch and Taylor, 1997). Differential learnability of grammatical systems, on the basis of learners’ exposure to triggering data from varying grammatical sources, causes change. This can be modelled as an evolutionary process in which variant source grammars provide competing constructions which are differentially-selected by the next generation of speakers as a consequence of properties of the LAD. Modelling language as an adaptive system which is the product of a changing population of language learners and users may shed light on the conditions under which parameters will be reset.

As Niyogi and Berwick (1997a,b) argue, the behaviour of all but the simplest dynamic systems is often unintuitive; whilst analytic proofs of the behaviour of classes of such systems are only possible when the number of variables involved is severely limited. For these reasons, a computational simulation methodology is utilized here, which allows more complex models to be studied experimentally. It is important that simulations strike the right balance between idealization and ecological validity, ignoring irrelevant complexities, but modelling potentially relevant factors, and making critical assumptions explicit. A simulation of linguistic evolution, at a minimum, needs to provide a source of linguistic variants on which selection can work and a realistic model of language acquisition which will form the basis of both the inheritance and selection amongst those variants. But before, developing such a model we need to consider the relationship between linguistic evolution and the biological evolution of the LAD.

1.3 Coevolution and Genetic Assimilation

Pinker and Bloom (1990) argue for an adaptationist account of the evolution of the language acquisition device (LAD) suggesting that the domain-specific linguistic (grammatical) knowledge required to support reliable language learning was geneti-

cally assimilated via natural selection for more successful language learners since the emergence of structured language.⁴ Genetic assimilation is a neo-Darwinian (and not Lamarckian) mechanism supporting apparent ‘inheritance of acquired characteristics’ (e.g. Waddington, 1942, 1975). The fundamental insights are that: 1) plasticity in the relationship between phenotype and genotype is under genetic control, 2) novel environments create selection pressures which favour organisms with the plasticity to allow within-lifetime developmental adaptations to the new environment, 3) natural selection will function to ‘canalize’ these developmental adaptations by favouring genotypic variants in which the appropriate trait develops reliably on the basis of minimal environmental stimulus, providing that the environment, and consequent selection pressure, remains constant over enough generations.⁵

As an example of genetic assimilation, Durham (1991) discusses in detail the case of widespread, though by no means universal, lactose tolerance in adult humans. Many of us, uniquely amongst mammals, continue to be able to easily digest milk after weaning. In many parts of the world the growth of animal husbandry created a new and reliable source of nutrition – milk. Thus, individuals more able to exploit this resource for longer periods of their lifetime were selected for. Lactose tolerance has been genetically assimilated by the great majority in populations where milk has been reliably available over many generations. Although it is not possible to relate lactose tolerance directly to specific genetic differences (yet), Durham demonstrates convincingly that the incidence of intolerance correlates, in a manner compatible with a genetic explanation, with a fairly recent introduction of dairy products and with warm climates, where lack of Vitamin D is less potentially problematic.⁶

Waddington, himself, suggested that genetic assimilation provided a possible mechanism for the gradual evolution of a LAD: ‘If there were selection for the ability to use language, then there would be selection for the capacity to acquire the use of language, in an interaction with a language-using environment; and the result of selection for epigenetic responses can be, as we have seen, a gradual accumulation of so many genes with effects tending in this direction that the character gradually becomes genetically assimilated.’ (1975:305f). Pinker and Bloom (1990) briefly make the same suggestion, citing Hinton and Nowlan’s (1987) computational simulation showing genetic assimilation of initial node settings facilitating learning in a population of neural networks.

One complication for this account of the evolution of the LAD is that it does

⁴This aspect of their argument, at least, is distinct from the question of whether the LAD originated via a biological saltation or gradually. Berwick (1997) argues that the Merge operation of the Minimalist Program (e.g. Chomsky, 1991) might have been exapted via genetic drift. This specific proposal is quite compatible with the framework presented here, in which function-argument application plays a similarly central role to Merge. Indeed, as Steedman (1996:14f) notes, the deterministic mapping via categorial rules of application, composition, and so forth from surface form to predicate-argument structure strengthens the case for an evolutionary pathway in terms of the development of such rules of ‘realization’ for pre-existing conceptual structures (see e.g. Bickerton, 1998; Worden, 1998). However, the question of the origin of the LAD, as opposed to its subsequent evolution and maintenance, is not addressed further in this paper.

⁵Waddington’s work on genetic assimilation is a neo-Darwinian refinement of an idea independently discovered by Baldwin, Lloyd Morgan and Osborne in 1896, and often referred to as the Baldwin Effect (see Richards, 1987 for a detailed history). Waddington refined the idea by emphasizing the role of canalization and the importance of genetic control of ontogenetic development – his ‘epigenetic theory of evolution’. He also undertook experiments with *Drosophila subobscura* which directly demonstrated modification of genomes via artificial environmental changes (see Jablonka and Lamb, 1995:31f for a detailed and accessible description of these experiments).

⁶Evolutionary biologists accept the possibility of genetic assimilation (e.g. Maynard Smith, 1987, 1993:319f; Rose, 1997:217f), however, some (e.g. Dawkins, 1982:284) regard it as a ‘hypothetical’ mechanism because, though it has been demonstrated experimentally, it has not been conclusively shown to occur naturally. It is extremely difficult to prove a case of natural, adaptive genetic assimilation. Nevertheless, the developmental view of evolution, which Waddington pioneered, is gaining ground as more is understood about the relationship between genes and environment in morphogenesis (e.g. Jablonka and Lamb, 1995).

not explain why genetic assimilation should not have continued until the point where a fully-specified grammar had been assimilated, and grammatical learning became redundant. Waddington (1975:307) remarks: ‘Evolution is quite capable of performing such a feat... But in the case of language, there is certainly little reason to see why it would have been advantageous to press the matter further. If a child which had never met a language-user developed the ability to talk, who after all would it talk to?’ Nevertheless, the propensity to use a fully-specified grammar, given minimal triggering input, would simplify the language acquisition problem to one of vocabulary acquisition. Pinker and Bloom (1990), following Hinton and Nowlan (1987), argue that selection pressure to set the remaining initial nodes in Hinton and Nowlan’s neural networks is weak once networks have evolved to learn reliably. However, Harvey (1993) demonstrates that this is an artifact of Hinton and Nowlan’s simulation design – later more effective networks almost invariably evolve, without mutation, from a single ancestor, causing ‘premature’ (and artifactual) fixation of some unset nodes, and thus preventing the population from evolving further. As long as there is selection pressure for a fully-developed capacity, we would expect no learning, and thus no delay in acquisition of the trait, to be the optimal solution.⁷

Deacon (1997:102f,327f) rejects any account of the evolution of a LAD via genetic assimilation, on the basis that genetic assimilation requires an unchanging environment to create the sustained selection pressure over the many generations required for genotypic adaptation. Pinker and Bloom (1990) simply assume that linguistic universals are evidence of enough constancy in the environment to allow genetic assimilation. However, once we view language itself as an adaptive system, this assumption, that universals are unambiguous evidence of genetic assimilation of linguistic knowledge into a LAD, is no longer necessarily valid. Deacon (1997:116f) instead argues for the contrary position that all linguistic ‘universal[s]... emerged spontaneously and independently in each evolving language, in response to universal biases in the selection processes affecting language transmission. They are *convergent* features of language evolution in the same ways as dorsal fins of sharks, ichthyosaurs, and dolphins are independent convergent adaptations of aquatic species.’ He suggests, in particular, that languages have evolved to be easily learnable by an acquisition procedure which ‘starts small’, following Elman (1993) discussed in section 1.1, with a limited working memory only capable of ‘seeing’ local grammatical dependencies. Furthermore, Deacon (1997:328f) argues that the surface grammatical organization of languages changes with such speed relative to genetic evolution that there could not have been consistent enough selection pressure for genetic assimilation.

Deacon’s position can be criticized on three levels. Firstly, it is unclear that he recognizes the import of linguistic learnability arguments and the relevance of abstract universals (without clear ‘surface’ effects). For example, the language acquisition procedure presented below can parse and learn grammatical constructions involving cross-serial grammatical dependencies, such as those exemplified in the formal language $a^n b^n c^n$ (where $n \geq 1$), Swiss German syntax and Bambara morphology (e.g. Shieber, 1985; Gazdar 1988), but not constructions involving the MIX or Bach language variant in which any ordering of equal numbers of the *as*, *bs* and *cs* is grammatical, creating arbitrarily intersecting dependencies. Whether a language exhibits cross-serial or arbitrarily intersecting dependencies is an apparently rather abstract feature which does not fit well into traditional more ‘surfacy’ characterizations of languages as, say, inflecting, agglutinating or isolating, or head-

⁷Ackley and Littman (1991) and Cecconi *et al.* (1996) describe unrelated simulations which, unlike Hinton and Nowlan, distinguish phenotype and genotype, do not make use of a fixed externally-defined fitness function, and do model learning cost – in these simulations learning is eventually entirely displaced, given a constant environment, as expected.

initial / final, and so forth. Nevertheless, this has profound consequences for the kind of rule system capable of expressing the mapping from SF to LF. Not least, that a formal proof of learnability has been found for grammatical frameworks capable of expressing cross-serial dependencies (Joshi *et al.*, 1991), but not for those able to express arbitrarily intersecting dependencies. The genetic assimilation of a language-specific rule *system* (the UG component of the LAD) remains a theoretical possibility, even if the emergence of such abstract universals can be traced to non-domain-specific factors, such as working memory limitations (see also Kirby, 1998).

Secondly, Deacon relies heavily on the ‘starting small’ hypothesis and Elman’s (1993) experiments training recurrent neural networks (RNN) to approximate recognition of context-free languages. Whilst these experiments demonstrate a clear requirement for initially training on short sequences containing local grammatical dependencies, it is unclear what consequences this has for grammatical acquisition by human learners. Elman’s RNN models do not have the expressive power to encode SF-LF mappings and, therefore, to underpin a model of language generation and interpretation. It is not, *a priori* obvious that when we move to consider models with this capacity, and their associated acquisition procedures, that a similar effect will be observed. In fact, though the experiments reported in sections 4.1 and 7 do show that the assumption of maturational memory limitations during language acquisition does affect predictions concerning the differential learnability of languages in the framework developed here, they do not show any effect on the learnability of languages *per se*.

Thirdly, in recent years, the increased use of mathematical tools and computational simulation has demonstrated the probability of extensive coevolutionary interactions across species, such as predator-prey interactions, competitive and benign host-parasite interactions, plant-insect interactions, and so forth (e.g. Futuyma and Slatkin, 1983; Kauffman, 1993:242f; Maynard Smith, 1998:285f). Most of these interactions involve species evolving at different rates, as the lifespan of the parasite is usually far shorter than that of the host. Though Waddington’s neo-Darwinian mechanism of genetic assimilation remains the basis for (co)evolution in response to environmental change, this work suggests that relative speed alone cannot conclusively be used to reject the possibility of genetic assimilation in response to pressure from an evolving linguistic environment. Interestingly, though Deacon (1997:112-13) draws the analogy between language and symbiotic bacteria (for example, those found in the human gut which aid digestion) and subtitled his book ‘co-evolution of language and brain’, he does not explicitly discuss the recent literature on coevolution, or whether this might warrant reconsideration of how environmental changes affect genetic assimilation. The speed at which linguistic changes can diffuse through a population will be far faster than that at which genetic change can do so. However, there is clearly a speed limit to this change within a successfully communicating population, and that speed limit means that only a small part of the space of possible grammars may be sampled over the period required for biological evolution. The experiments reported in section 7 suggest this can lead to a constant enough selection pressure capable of supporting genetic assimilation of a LAD. However, the fact of linguistic change provides a natural barrier to total genetic assimilation of a fully-specified grammar.

The simulation models both natural selection for variant language acquisition procedures and linguistic selection for languages. Therefore, it is possible to both explore what kind of acquisition procedure might evolve and what effects different acquisition procedures might have on the grammatical systems which evolve, given varying assumptions about the role of memory limitations in learning, the adaptive advantage of language to language users, and so forth (Briscoe, 1997, 1998a,b). The simulation can be set up to model either a neutral, random relationship or benign,

symbiotic relationship between languages and their potential users. That is, one in which the ability to communicate via language either confers no selective advantage (or disadvantage) or one which confers some (unspecified) selective advantage to its users. Additionally, in some experiments, the ability to communicate using a more learnable, expressive or interpretable variant language can confer greater relative advantage. Roughgarden (1983) argues that mutualistic coevolution between ‘host’ (language users) and ‘guest’ (language idiolects) organisms will only occur when the host benefits (and the experiments reported in section 6 bear out this prediction).

On the assumption that language confers selective advantage, linguistic variants will compete for language users on the basis of their relative learnability, and, possibly their interpretability and/or expressiveness. Language users will also evolve language faculties which improve their capacity to acquire and use language. Given this scenario, a language can be viewed as a parasitic coevolving species. Under the alternative assumption that language confers no selective advantage, linguistic variants will compete for language users solely on the basis of their learnability with respect to whatever acquisition procedure is in place. However, there will be no pressure for this acquisition procedure to evolve to favour any particular linguistic variants. Thus, a language can still be seen as a dynamic system adapting to the requirements of learnability, but language will have no influence on biological evolution. Nevertheless, given the implausibility of assuming that language confers no selective advantage, whatever form this might take, the coevolutionary scenario seems more likely.

There are several ways in which linguistic evolution and biological evolution might be argued to be qualitatively different, in addition to such quantitative differences as relative speed of change. Linguistic variants may compete for language users, but it might be argued they do not have a fitness, in the technical sense of expected number or proportion of offspring (e.g. Maynard Smith, 1998:36f). Rather the primary mechanism of linguistic inheritance is through a child language learner *actively* learning their idiolect, rather than the gene replicating via the medium of DNA (e.g. Keller, 1994). The degree to which this distinction can be upheld depends on the extent to which a gene is defined as a biochemical object, as opposed to a unit of information.⁸ In the simulation model, language users may have (relative) fitness as a consequence, primarily, of their communicative success, whilst languages have (relative) cost to users depending, primarily, on their fit with their acquisition procedures. A different but related question concerns the units of linguistic selection, and whether there can be a corresponding distinction between phenotype and genotype in linguistic evolution. Linguistic variation is defined in terms of *competing* constructions which form part of the linguistic environment (or phenotype). Such variants compete by virtue of being in parametric variation or, perhaps more generally, because they are variant means of expressing the same meaning. In terms of the model of the LAD developed in section 2 and simulation model of section 3, the principles and parameters which define UG and specific grammars form the ultimate units of linguistic selection.

2 The Language Acquisition Device

A model of the LAD incorporates a UG with associated parameters, a parser, and an algorithm for updating initial parameter settings on parse failure during acquisition (e.g. Clark, 1992). The following sections present such a model, which builds on and extends previous work reviewed in section 1.1.

⁸Dawkins (1982:109f) and Dennett (1991:341f) make similar points discussing the differences between genes and memes (minimal ideational units of cultural inheritance putatively subject to cultural selection).

	Forward Application:
$X/Y \ Y \Rightarrow X$	$\lambda y [X(y)] (y) \Rightarrow X(y)$
	Backward Application:
$Y \ X \backslash Y \Rightarrow X$	$\lambda y [X(y)] (y) \Rightarrow X(y)$
	Forward Composition:
$X/Y \ Y/Z \Rightarrow X/Z$	$\lambda y [X(y)] \lambda z [Y(z)] \Rightarrow \lambda z [X(Y(z))]$
	Backward Composition:
$Y \backslash Z \ X \backslash Y \Rightarrow X \backslash Z$	$\lambda z [Y(z)] \lambda y [X(y)] \Rightarrow \lambda z [X(Y(z))]$
	(Generalized Weak) Permutation:
$(X Y_1) \dots Y_n \Rightarrow (X Y_n) Y_1 \dots$	$\lambda y_n \dots, y_1 [X(y_1 \dots, y_n)] \Rightarrow \lambda \dots y_1, y_n [X(y_1 \dots, y_n)]$

Figure 1: GCG Rule Schemata

2.1 The Grammar (set)

Classical (AB) categorial grammar uses one rule of application which combines a functor category (containing a slash) with an argument category to form a derived category (with one less slashed argument category). Grammatical constraints of order and agreement are captured by only allowing directed application to adjacent matching categories. Generalized categorial grammars (GCGs) extend the AB system with further rule schemata.⁹ The rules of forward application (FA), backward application (BA), generalized weak permutation (P) and forward and backward composition (FC, BC) are given in Figure 1 (where X, Y and Z are category variables, | is a variable over slash and backslash, and ... denotes zero or more further functor arguments). Generalized weak permutation enables cyclical permutation of argument categories, but not modification of their directionality. Each rule has an associated semantic operation represented here in terms of η conversion in the (typed) Lambda Calculus. Once permutation is included, several semantically equivalent derivations for *Kim loves Sandy* become available, Figure 2 shows the non-conventional left-branching one.¹⁰ Composition also makes alternative non-conventional semantically-equivalent (left-branching) derivations available, as Figure 3 illustrates. Steedman (1988, 1996) presents the arguments for the linguistic utility of composition.

GCG as presented is inadequate as an account of UG or of any individual grammar. In particular, the definition of atomic categories needs extending to deal with featural variation, further unary/lexical rules will be needed (e.g. Bouma and van Noord, 1994), and the rule schemata, especially C and P, must be restricted in various parametric ways so that overgeneration is prevented for specific languages (e.g. Morrill, 1994). Nevertheless, GCG does represent a plausible kernel of UG;

⁹Wood (1993) is a general introduction to categorial grammar and possible extensions to the basic theory. The most closely related theories to that presented here are those of Steedman (e.g. 1988, 1996) and especially Hoffman (1995, 1996).

¹⁰Generalized weak permutation (P) is more powerful than the rule sometimes called associativity (e.g. Wood, 1993:37f) which licenses $(X/Y) \backslash Z \Rightarrow (X \backslash Z)/Y$ but not $(X/Y)/Z \Rightarrow (X/Z)/Y$, since the latter is also licensed by P. However, P is less powerful than permutation in the extended Lambek calculus **LP** (e.g. Wood 1993:64f; Moortgat, 1988:45f) in which directional constraints are no longer maintained – see Briscoe, 1998b for a more detailed exploration and justification of the consequences of P.

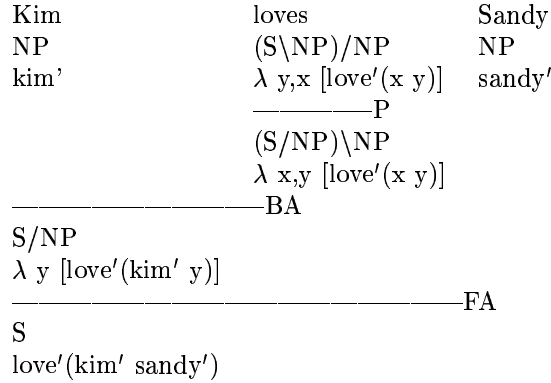


Figure 2: GCG Derivation for *Kim loves Sandy*

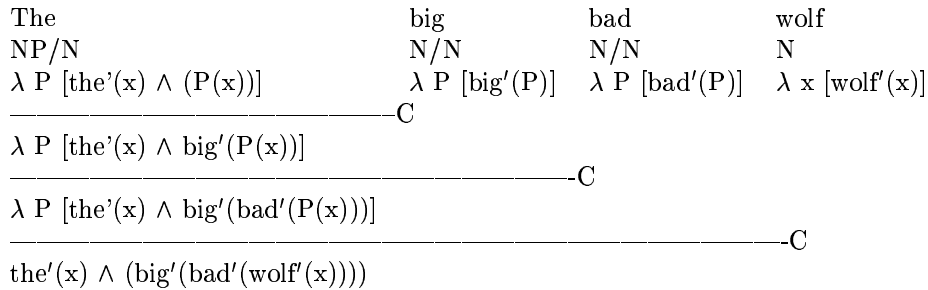


Figure 3: GCG Derivation for *The big bad wolf*

Hoffman (1995, 1996) explores the descriptive power of a very similar system, in which P is not required because functor arguments are interpreted as multisets. She demonstrates that this system can handle (long-distance) scrambling elegantly and generate some mildly context-sensitive, though not some MIX, languages (Joshi *et al*, 1991).

The relationship between GCG as a theory of UG (GCUG) and as a specification of a particular grammar is captured by embedding the theory in a default inheritance network.¹¹ Figure 4 illustrates schematically and informally a fragment of a such a network. The network defines intensionally the set of possible categories and rule schemata via type declarations on nodes. For instance, an intransitive verb is treated as a subtype of verb, inheriting subject directionality by default from a type **gendir** (for general direction). For English, **gendir** is default **right** (/) but the node of the (intransitive) functor category, where the directionality of subject arguments is specified (**subjdir**), overrides this to **left** (\), reflecting the fact that English is predominantly right-branching, though subjects appear to the left of the verb. A transitive verb inherits its structure from the type for intransitive verbs and an extra NP argument with default directionality specified by **gendir**, and so forth. A full specification of English will also declare English verbs, such as *smile*

¹¹This can be formalized as a semi-lattice of typed default feature structures (TDFSs) representing subsumption and default inheritance relationships (Lascarides *et al*, 1996; Lascarides and Copestake, 1996, in press) supporting multiple orthogonal (default) inheritance. The TDFS formalism allows absolute specification, default specification, or unset values in feature structures. These possibilities correspond to inherited principles and default-valued or unset parameters, respectively.

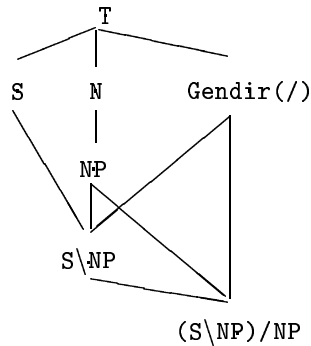


Figure 4: Network fragment for a category set

N	NP	S	gen-dir	subj-dir	applic
A T	A T	A T	D R	D L	D T
N	gendir	applic	S	NP	subj-dir
A T	D R	D T	A T	A T	D L
applic	N	NP	gen-dir	subj-dir	S
D T	A T	A T	D R	D L	A T
...					

Figure 5: Sequential encodings of the network fragment

and *love*, to be instances of the appropriate categories (types). Wood (1993) further discusses techniques for embedding categorial grammars, including rule schemata, in constraint / unification-based representation languages.

For the purposes of the evolutionary simulation described in section 3, GC(U)Gs are represented as a sequence of *p-settings* (where *p* denotes principles or parameters) based on a flat (ternary) sequential encoding of such default inheritance networks. The inheritance network provides a partial ordering on parameters, which is exploited in the acquisition procedure. For example, the atomic categories, **N** and **S** are each represented by a parameter encoding the presence / absence or lack of specification (T(rue)/F(alse)/U(nset)) of the category in the (U)G. Since they are unordered in the semi-lattice, their ordering in the sequential coding is arbitrary. However, the ordering of the directional types **gendir** and **subjdir** (with values L(eftrightarrow)/R(ight)) is significant as the latter is a more specific type. The distinctions between absolute, default or unset specifications also form part of the encoding (A/D/?). Figure 5 shows several equivalent and equally correct sequential encodings of the fragment of the English type system described above.

A set of grammars, based on typological distinctions defined by basic constituent order (e.g. Greenberg, 1966; Hawkins, 1994), was defined as a (partial) GCUG with binary-valued parameters encoding order, and several others encoding, for example, the availability of P during a derivation. The eight basic language families are defined in terms of the unmarked, canonical order of verb (V), subject (S) and objects (O). Languages within families further specify the order of modifiers and specifiers in phrases, the order of adpositions, and further phrasal-level ordering parameters. Figure 6 lists the language-specific ordering parameters used to define the full set of grammars in left-to-right partial order of generality, and gives examples of settings based on familiar languages such as SVO, “English”, SOVv2, “German”, and SOV,

	gen	v1	n	subj	obj	v2	mod	spec	relcl	adpos	compl
SVO	R	F	R	L	R	F	R	R	R	R	R
SOVv2	R	F	R	L	L	T	R	R	R	R	R
SOV	L	F	L	L	L	F	L	L	L	L	?

Figure 6: The Grammar/Language Set – Ordering Parameters

“Japanese”.¹² “English” is an SVO language with prepositions, in which specifiers, complementizers and some modifiers precede heads of phrases. In the figure, ‘R’ and ‘L’ are mnemonic for left/right and ‘T’ and ‘F’ for true/false or on/off. The left/right specifications refer to the directionality encodings on functors; for example, in “English” specifiers are functors looking for (nominal) arguments to their right, whilst relative clauses are treated as arguments of categories like NP/Rc and thus, this functor (**relcl**) is also rightward. There are other grammars in the SVO family in which all modifiers follow heads, there are postpositions, and so forth. Not all combinations of parameter settings correspond to attested languages and one entire language family (OSV) is either unattested or extremely rare (see Pullum, 1981). “Japanese” is an SOV language with postpositions in which specifiers and modifiers follow heads. There are other languages in the SOV family with less consistent left-branching syntax in which specifiers and/or modifiers precede phrasal heads, some of which are attested. “German” is a more complex SOV language in which the verb-second (v2) parameter ensures that the surface order in main clauses is usually SVO.¹³

There are 20 p-settings which determine the rule schemata available, the atomic category set, and the ‘shape’ of functor categories. In all, this CGUG defines just under 300 grammars. Not all of the resulting languages are (stringset) distinct and some are proper subsets of other languages. “English” without the rule of permutation results in a weakly-equivalent stringset-identical language, but the grammar assigns different derivations to some strings, though the associated LFs are identical. “English” without composition results in a proper subset language. Some combinations of p-settings result in ‘impossible’ grammars (or UGs). Others yield equivalent grammars, for example, different combinations of default settings (for types and their subtypes) can define an identical category set.

The grammars defined generate (usually infinite) stringsets of lexical syntactic categories. These strings are sentence types since each defines a finite set of grammatical sentences (tokens), formed by selecting a lexical item consistent with each lexical syntactic category. Such sequences of lexical syntactic categories can be viewed as triggers (determinate SF-LF pairings) because in this framework knowing the lexical syntactic category of each word in a sentence is enough to deterministically recover an unscoped LF. Languages are represented as a finite subset of sentence types generated by the associated grammar. These are a proper subset of the degree-0 triggers for the language (Lightfoot, 1992:22f). Subset languages are

¹²Throughout double quotes are used around language names, as convenient mnemonics for familiar combinations of parameters. Since not all aspects of these actual languages are represented in the grammars, conclusions about actual languages must be made with care.

¹³Representation of the v1 and v2 parameters in terms of type constraints determining allowable verbal functor categories is discussed in more detail in Briscoe (1998b). Briefly, v1 corresponds to verbs being assigned two categories allowing initial and medial position, as in “Welsh”, SVOv1, in conjunction with a relaxation of default ordering of the argument interpreted as subject being ‘outermost’ (*arg0*), as for canonical VSO. Whilst, v2 is encoded by requiring auxiliary verbs to take an underspecified NP argument to their left and a (S\NP) argument to their right with features and interpretation of this missing NP in the main verb’s argument list bound to the leftward argument of the auxiliary, as in “German”, SOVv2.

exemplified by between 3 and 9 such sentence types and full languages by 12 sentence types. The constructions exemplified by each sentence type and their length are equivalent across all the languages defined by the grammar set, but the sequences of lexical categories can differ. For example, two SOV language renditions of a sentence type / trigger corresponding to *The man who Bill likes gave Fred a present*, one with premodifying and the other postmodifying relative clauses, both with a relative pronoun at the right boundary of the relative clause, are shown below with the differing category highlighted.

Bill likes who the-man a-present Fred gave
 $NP_s (S \setminus NP_s) \setminus NP_o \text{ Rc} \setminus (S \setminus NP_o) \mathbf{NP}_s \setminus \mathbf{Rc} NP_{o2} NP_{o1} ((S \setminus NP_s) \setminus NP_{o2}) \setminus NP_{o1}$

The-man Bill likes who a-present Fred gave
 $\mathbf{NP}_s / \mathbf{Rc} NP_s (S \setminus NP_s) \setminus NP_o \text{ Rc} \setminus (S \setminus NP_o) NP_{o2} NP_{o1} ((S \setminus NP_s) \setminus NP_{o2}) \setminus NP_{o1}$

The expressiveness of a grammar / language is modelled (crudely) in terms of the proportion of sentence types which can be generated and parsed from the finite subset for the associated full language.

2.2 The Parser

The parser uses a deterministic, bounded-context shift-reduce algorithm (see Briscoe, 1987, 1998b for further details and justification). It represents a simple and natural approach to parsing with GCGs which involves no grammar transformation or precompilation operations, and which directly applies the rule schemata to the categories defined by a GCG. The parser operates with two data structures, an input buffer or queue, and a stack or push down store. Lexical categories are shifted from the input buffer to the analysis stack where reductions are carried out on the categories in the top two cells of the stack, if possible. When no reductions are possible, a further lexical item is shifted onto the stack. When all possible shift and reduce operations have been tried, the parser terminates either with a single ‘S’ category in the top cell, or with one or more non-sentential categories indicating parse failure. The algorithm for the parser working with a GCG which includes application, composition and generalized weak permutation is given in Figure 7.

A parse history analysing *Kim loves Sandy* is shown in Figure 8. The first two columns show the state of the stack and buffer after each step. The third column names the operation which has applied to produce the state shown at this step. The final column gives the step number. A similar approach to parsing GCGs is sketched by Ades and Steedman (1982), and Briscoe (1987) describes a closely related parser in more detail. This algorithm finds the most left-branching derivation for a sentence type because Reduce is ordered before Shift. In Figure 8 this results in *Kim loves* being reduced to a functor from NPs to Ss by permutation on the category for *loves*, and then application. The algorithm also finds the derivation involving the least number of parsing operations because only one round of permutation occurs each time application and composition fail.¹⁴ The category sequences representing the sentence types in the data for the entire language set are designed to be unambiguous relative to this ‘greedy, least effort’ algorithm, so it will always assign the appropriate LF to each sentence type. However, there are frequently alternative less left-branching or more ‘expensive’ derivations of the same LF, and in some cases a distinct LF could be recovered by generating all permutations of functors before attempting application / composition. For example, if permutation

¹⁴The preference for left-branching derivations and those involving the least number of parsing operations can be seen as a precise and computationally-tractable instantiation of an analogue of the Economy Principle of the Minimalist Program (e.g. Chomsky, 1991:447f) within this framework.

1. THE REDUCE STEP: if the top 2 cells of the stack are occupied, then try
 - a) Application, if match, then apply and goto 1), else b),
 - b) Composition, if match then apply and goto 1), else c),
 - c) Permutation, if match then apply and goto 1), else goto 2)
2. THE SHIFT STEP: if the first cell of the Input Buffer is occupied, then pop it and move it onto the Stack together with its associated lexical syntactic category and goto 1), else goto 3)
3. THE HALT STEP: if only the top cell of the Stack is occupied by a constituent of category S, then return Success, else return Fail

THE MATCH AND APPLY OPERATION: if a binary rule schema matches the categories of the top 2 cells of the Stack, then they are popped from the Stack and the new category formed by applying the rule schema is pushed onto the Stack.

THE PERMUTATION OPERATION: each time step 1c) is visited during the Reduce step, permutation is applied to one of the categories in the top 2 cells of the Stack (until all possible permutations of the 2 categories have been tried in conjunction with the binary rules). The number of possible permutation operations is finite and bounded by the maximum number of arguments of any functor category in the grammar.

Figure 7: The Parsing Algorithm

is not available to the parser at step 3 in Figure 8, the parser will fail to reduce, and instead shift *Sandy* onto the stack, reducing *loves Sandy* first.

The parser is augmented with an algorithm which computes working memory load during an analysis. This algorithm is based on three uncontroversial features of human working memory. Firstly, working memory is limited, as evidenced, for example, by people’s inability to remember sequences of more than a few unrelated digits. Secondly, there is a strong recency effect on working memory which ensures that recent or recently-revisited elements of a sequence are better recalled. And thirdly, the greater the degree of analysis or depth of processing of elements, the greater the chance of recall (see section 1.1 and Baddeley,1976; 1992).

Limitations of working memory are modelled in the parser by associating a cost with each stack cell occupied during each step of a derivation, and recency and depth of processing effects are modelled by resetting this cost each time a reduction occurs: the working memory load (WML) algorithm is given in Figure 9. Figure 10 gives the right-branching derivation for *Kim loves Sandy*, found by the parser utilizing a grammar without permutation. The WML at each step is shown for this derivation. The overall WML (16), found by summing the WML at each step, is higher than for the left-branching derivation (9).

The WML algorithm ranks sentence types, and thus indirectly languages, by parsing each sentence type from the data exemplifying each language with the associated grammar and then taking the mean of the WML obtained for all exemplifying sentence types. “English” with permutation has a lower mean WML than “English” without permutation, though they are stringset-identical, whilst a hypothetical mixture of SOV clausal order with “English” phrasal syntax has a mean WML which is 25% worse than that for “English”. The parser and WML algorithm are broadly

Stack	Input Buffer	Operation	Step
	Kim loves Sandy		0
Kim:NP:kim'	loves Sandy	Shift	1
loves:(S\NP)/NP: $\lambda y,x(\text{love}' x, y)$ Kim:NP:kim'	Sandy	Shift	2
Kim loves:S/NP: $\lambda y(\text{love}' \text{kim}', y)$ Sandy:NP:sandy'	Sandy	Reduce (P,A)	3
Kim loves:S\NP: $\lambda y(\text{love}' \text{kim}', y)$		Shift	4
Kim loves Sandy:S:($\text{love}' \text{kim}', \text{sandy}'$)		Reduce (A)	5

Figure 8: Parsing *Kim loves Sandy*

After each parse step (Shift, Reduce, Halt (see Fig 7):

1. Assign any new Stack entry in the top cell (introduced by Shift or Reduce) a WML value of 0
2. Increment every Stack cell's WML value by 1
3. Push the sum of the WML values of each Stack cell onto the WML-record

When the parser halts, return the sum of the WML-record which gives the total WML for a derivation.

Figure 9: The WML Algorithm

in accord with existing psycholinguistically and typologically motivated theories of parsing complexity (e.g. Briscoe, 1987,1998b; Gibson, 1991; Hawkins, 1994; Rambow and Joshi, 1994). The combination of GCG and shift-reduce bounded-context parsing allows a fully incremental interpretation (e.g. Milward, 1995) and, although the model as presented here, is deterministic, it could be straightforwardly extended to a nearly-deterministic interactive parser (Briscoe, 1987) or a bounded parallel parser (Gibson, 1991) in order to model the resolution of ambiguity.

2.3 The Parameter Setting Algorithm

The parameter setting algorithm is an extension and modification of Gibson and Wexler's (1994) Trigger Learning Algorithm (TLA) to take account of the inheritance-based partial ordering, the role of memory in learning, variant criteria for retaining new parameter settings, and so forth. The TLA is error-driven – parameter settings are altered in constrained ways when a learner cannot parse trigger input and when the alteration results in a successful parse. Trigger input is defined as primary linguistic data which, because of its structure or context of use, is determinately unparseable with the correct interpretation.

The TLA is memoryless in the sense that a history of parameter updates is not maintained, in principle, allowing the learner to revisit previous hypotheses. This is what allows Niyogi and Berwick (1996) to formalize parameter setting as a Markov process. However, as Brent (1996) argues, the psychological plausibility of this algorithm is doubtful – there is no evidence that children blindly move between neighbouring grammars along paths that revisit previous hypotheses. Therefore, in the modified algorithm each parameter can only be updated once during the acquisition process, resulting in a learning procedure with (limited) memory. As Brent

Stack	Input Buffer	Operation	Step	WML
	Kim loves Sandy		0	0
Kim:NP:kim'	loves Sandy	Shift	1	1
loves:(S\NP)/NP: $\lambda y,x(\text{love}' x, y)$	Sandy	Shift	2	1
Kim:NP:kim'				2 (=3)
Sandy:NP:sandy'		Shift	3	1
loves:(S\NP)/NP: $\lambda y,x(\text{love}' x, y)$				2
Kim:NP:kim'				3 (=6)
loves Sandy:S/NP: $\lambda x(\text{love}' x, \text{sandy}')$		Reduce (A)	4	1
Kim:NP:kim'				4 (=5)
Kim loves Sandy:S:($\text{love}' \text{kim}'$, sandy')		Reduce (A)	5	1

Figure 10: WML for *Kim loves Sandy*

points out, this results in a *consistent* algorithm which utilizes triggers in the most efficient manner possible to traverse the search space. However, because of the use of default specification in the grammatical representation language, this does not lead to strictly monotonic refinement of grammatical hypotheses. Thus, despite the ordered acquisition procedure, the sequence of hypothesized grammars can involve overriding or retraction of decisions, because parameters encode a *default* inheritance network. For example, a learner of German can incorrectly hypothesize a SVO grammar by updating **gendir** to R(ight) and **subjdir** to L(eft), but subsequently override this and hypothesize underlying SOV by resetting **objdir** to L(eft). Now the default effects of **gendir** will only apply (correctly) within phrasal ordering – see e.g. Clark (1992) for discussion of the indeterminacy of parameter expression and its consequences for learnability. Meisel (1995) argues that a limited memory which prevents resetting of parameters already updated by the learner is essential for any account of the acquisition of core grammar given the presence of a marked periphery of constructions.

The TLA is local in the sense that only one (random) parameter can be reset on parse failure. In the modified algorithm, sometimes this requirement is relaxed to n parameters per parse failure. Bertolo (1995) argues that this relaxation of the TLA does not alter fundamental results concerning local maxima and learnability. The motivation for relaxing the single-value constraint and adopting a n -local variant of the TLA is twofold: firstly, the selection of a fair sample of triggers / sentence types with respect to working memory load creates unbalanced trigger paths with respect to the number of parameter resettings required to successfully learn a given language; secondly, the parameter n can be varied in the evolutionary simulation, creating a wider range of acquisition procedures to select from.¹⁵

The TLA is unordered in the sense that on parse failure a parameter is chosen at random to be updated. In the modified algorithm, parameters are updated starting with the most general, in terms of the partial order defined by the inheritance network. Once updated they are not revisited because the procedure utilizes limited memory. The TLA is greedy in the sense that a parameter updated on parse failure is retained if that setting allows the current trigger to be reparsed successfully. The acquisition procedure can be made more incremental, as well as greedy, by relaxing the requirement that parameter updates must result in a completely successful parse

¹⁵To determine whether the grammar / language set explored can be learnt, in principle, by a non-incremental acquisition procedure with, say, n set to 1 would require an exhaustive specification of the set of potential triggers for each language – see Gibson and Wexler, 1994; Niyogi and Berwick, 1996. Because of the larger size of the grammar / language set explored here this would be a non-trivial undertaking which is beyond the scope of the current paper.

Data: $\{S_1, S_2, \dots S_n\}$

```

unless
  PARSEi(GRAMMARi(P-SETTINGi))(Sj) = Success
then
  p-settingj = UPDATE(p-settingi)
  unless
    PARSEj(GRAMMARj(P-SETTINGj))(Sj) = Success
  then
    RETURN p-settingi
  else
    RETURN p-settingj

```

UPDATE:

Reset the first n default parameter(s) or set the first n unset parameter(s) in a 'left-to-right' search of the p-settings (consistent with the partial order encoding their generality) according to the following table:

Input:	D 1	D 0	? ?
Output:	R 0	R 1	? 1/0

(where 1 = T/L and 0 = F/R – see figs. 5&6 above)

Figure 11: The Learning Algorithm

for the new setting(s) to be retained. Retaining a parameter update if it results in an improved parse, defined as the recovery of more of the target LF, results in a model closer to Dresher and Kaye's (1990) cue-based approach, as it places more emphasis on the degree of evidence provided by a trigger for an individual parameter setting, rather than on obtaining a successful parse. The acquisition procedure can be made maturational and incorporate the 'starting small' hypothesis (see section 1.1; Elman, 1993). The working memory load of a sentence type can be used to determine whether it can function as a trigger at a particular stage in learning, thus filtering random presentation of triggers and ensuring that triggers are presented in (partial) order of decreasing parsability.

Each step for a learner can be defined in terms of three functions: P-SETTING, GRAMMAR and PARSE, as:

$PARSE_i(GRAMMAR_i(P-SETTING_i(\text{Sentence}_j)))$

A p-setting defines a grammar which in turn defines a parser (where the subscripts indicate the output of each function given the previous trigger). A parameter is updated on parse failure and, if this results in a (better) parse, the new setting is retained. The algorithm is summarized in Figure 11. The core of the algorithm is the update rule, which is applied to a sequential p-setting encoding as described in section 2.3; for instance, a default parameter can be reset to its opposite value and the 'D' encoding changed to a 'R' to record that this default parameter has been reset, and so forth. In the experiments reported below, unset parameters are updated to the correct value required to parse the trigger. This has no implications for convergence of the acquisition procedures. Random setting of unset parameters would simply require more exposure to appropriate triggers, since settings are only retained if they result in a successful parse. However, the deterministic approach is used here in order not to (artificially) bias the simulation model towards a

preference for default initial settings.

In summary, this account of the parameter setting procedure is consistent, error-driven, greedy, possibly incremental, n -local, partially-ordered, utilizes limited memory, and can incorporate maturationally-developing working memory limitations. Finally, the initial configuration of the parameters in the TLA is usually taken to be any arbitrary grammar, though as Gibson and Wexler (1994) point out, assuming (some) specific unmarked initial settings can remove local maxima. In this model, parameters can be initially unset (?) or have a default (D) value (see section 2.3). The precise choice of parameters, of their initial settings, of the n (re)settable parameters per trigger, and of the update success criterion, defines a space of variant acquisition procedures for the experimenter (or the evolutionary simulation) to select from.¹⁶

The learnability of languages in the model is ranked in terms of the number of parameters that must be updated to converge to the target grammar, and also in terms of the maximum number of parameters which must be updated for a single trigger given an optimal presentation sequence of triggers to a non-incremental procedure. This ranking is calculated by assuming a learner with all parameters unset initially (see section 4 below). However, the ranking can also be made more dynamic by recalculating it for different potential initial p-settings and acquisition procedures.

3 The Evolutionary Simulation

The computational simulation supports the evolution of a population of Language Agents (LAGts), similar to Holland's (1993, 1995) Echo Agents, but equipped with a LAD, as described in section 2, and a simple sentence generator based on (usually random) generation of a trigger / sentence type from the LAGt's current idiolect (if any).¹⁷ LAGts generate and parse sentence types compatible with their current p-settings. They participate in linguistic interactions which are communicatively successful if their p-settings are compatible. Compatibility is defined in terms of the ability to map from a given SF to the same LF, rather than in terms of sharing of an identical grammar.¹⁸ LAGts are either learning a grammar, or have completed learning and fixed on the grammar and associated idiolect acquired at that point.

In experiments which utilize natural (biological) selection for LAGts, the relative fitness of a LAGt is a function of the proportion of its linguistic interactions which have been successful, and optionally of the learnability, expressiveness and/or interpretability of the grammar(s) / idiolect(s) used by that LAGt during a cycle of interactions. Thus, fitness is dependent on an agents' linguistic compatibility with other agents, creating a form of frequency-dependent selection (e.g. Maynard Smith, 1998:69f), and also potentially on the complexity of the grammar /

¹⁶In the simulation, sentence types used as triggers are represented by p-setting schemata with associated memory loads to avoid the need for continuous on-line parsing of triggers. Thus, the model largely circumvents issues of indeterminacy in parameter expression, the need to deal with 'noise' in the input, and any consequent errors by the learner (see Clark, 1992). Nevertheless, the current model can be extended to deal with noise and indeterminacy by embedding it in a statistical learning framework (Kapur and Clark, 1994; Briscoe, 1998b), though this would involve abandoning the strictly ordered, consistent acquisition procedure presented here.

¹⁷It should, therefore, be clear that the model does not attempt to characterize the emergence or origin of the LAD. It assumes a prior population of 'Saussurean' LAGts, to use Hurford's (1989) term, with at least the capacity to represent and learn word:meaning associations, and with the basic architecture of a LAD.

¹⁸P-setting compatibility implements a weak notion of communicative success. Thus, there is no Gricean entailment of successful transmission of speaker intentions, or of a shared interpretation. Consequently, the model builds in no strong assumptions about the function(s) of language, whether this be to influence others, communicate (mis)information, or whatever (see e.g. Pinker and Bloom, 1990; Keller, 1994:84f for insightful discussion).

idiolect(s) internalized. Learnability is modelled in terms of the number of parameters which need to be set to acquire a target grammar, the highest number which need to be updated for a single trigger, and the agent’s success rate at correctly setting parameters. Learning time, and thus the time taken to achieve maximal communicative success, can also be increased by additional maturational memory limits during learning. However, this cost might also be offset by the tendency of such limits to create a more optimal presentation of triggers to the acquisition procedure. Interpretability is modelled by parsing cost measured in terms of mean working memory load created during an interaction cycle, according to the WML model of section 2.2. Expressiveness is modelled (crudely) in terms of an additional (graded) cost for using a proper subset language of one of the 70 full languages defined by the grammar space. This fitness component is needed in some experiments because otherwise LAgts tend to converge on less expressive languages with lower mean WML costs and less parameters to set. In general, the pressures created for learnability, parsability and expressiveness are conflicting, creating the potential for complex interactions and trade-offs in the search for (locally) optimal languages.

An interaction cycle consists of a prespecified proportion of individual random interactions between LAgts, with generating and parsing agents also selected randomly. When natural selection is used, LAgts which have a history of mutually successful interaction and higher than average fitness can ‘reproduce’; otherwise LAgts reproduce randomly. A LAgts ‘lives’ for ten interaction cycles. It is possible for a population to become extinct (for example, if all the initial LAgts go through ten interaction cycles without any successful interaction occurring), and successful populations tend to grow at a modest rate (to ensure a realistic proportion of adult speakers is always present). LAgts learn during a critical period from ages 1-4 (defined in terms of interaction cycles) and reproduce from 3-10, parsing and/or generating any idiolect learnt throughout their life.¹⁹

During learning, a LAgts can reset genuine parameters which either were unset or had default settings ‘at birth’. However, p-settings with an absolute value (principles) cannot be altered during the lifetime of an LAgts. This is the manner in which the distinction between principles, or universal grammar (the genetic endowment), and parameters, to be updated during the acquisition of a particular grammar, is modelled. Successful LAgts reproduce at the end of interaction cycles by one-point crossover of (and, optionally, single point mutation of) their *initial* p-settings – ensuring neo-Darwinian rather than Lamarckian inheritance; that is, LAgts inherit (a composite of) their parents’ genetic endowment and not their acquired (learnt) characteristics.²⁰ In reproduction there is a high chance of the reproducing LAgts p-settings being mixed by crossover, where the p-settings are cut and cross-spliced at a randomly chosen point. There is also, in some experiments, a low chance of a single element in the resulting p-setting being mutated to an alternative value. Fitness-based reproduction ensures that successful and somewhat compatible p-settings are preserved in the population and continually resampled in the search for better versions of UG, including better initial settings of genuine parameters. Thus, although the parameter setting algorithm *per se* is fixed, a range of alternative acquisition procedures can be explored based on the definition of the set of parameters, their initial settings, and optionally mutation of the *n* updatable parameters per trigger. Crossover and mutation can turn an absolute (inherited) principle into a default or unset parameter and vice versa, change values of either, and so forth.²¹

¹⁹The critical period is simply stipulated – Hurford (1991) and Hurford and Kirby (1997) describe evolutionary simulations in which such a critical period emerges given certain assumptions.

²⁰The encoding of p-settings allows the deterministic recovery of the initial setting because reset parameters are those preceded by ‘R’, or ‘?’ followed by a determinate value. ‘?’ parameters are reset to unset values and default ‘R’ parameters are reset again to the opposite value.

²¹The use of crossover and mutation operators with the p-setting code is based on genetic

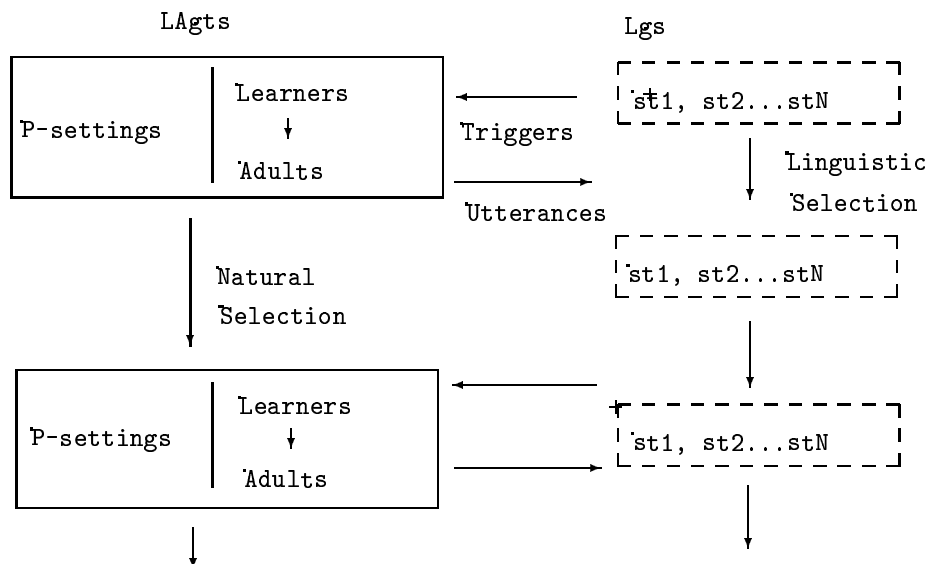


Figure 12: The Simulation Model

In experiments investigating linguistic selection, there is a need to provide a source of linguistic variation. In reality, variation is generated by language contact and borrowing, linguistic innovation, reanalysis during learning, and so forth (see e.g. Harris and Campbell, 1995; Milroy, 1992). In the simulation, this is modelled by introducing additional adult LAGts with a different full language at regular intervals, or by initializing the simulation with two genetically-identical adult groups speaking different full languages. That is, all variation is a consequence of population movement and no attempt is made to model the actuation of linguistic change.

Figure 12 illustrates the model graphically. There are two interacting evolving domains of LAGts and of languages. Selection for languages operates on sentence types ($st_1, st_2 \dots st_N$) some of which act as triggers during language learning by LAGts. Linguistic selection is either simply in terms of the learnability of triggers or more generally in terms of the parsability and expressiveness of sentence types for all LAGts, depending on the fitness function utilized. Thus, the pool of sentence types in the linguistic arena of use (Hurford, 1987) changes over time as LAGts select from language variants. The ultimate units of linguistic evolution are the principles and parameters encoded in LAGts' p-settings, but selection operates directly on sentence types or constructions. This is the analogue of the distinction between phenotype and genotype in linguistic evolution. Natural selection operates on LAGts and is driven principally by their communicative success but can also take account of the working memory resources used in parsing and their expressiveness, depending on the fitness function utilized. The ultimate units of biological evolution are the *initial* configurations of their p-settings prior to learning. As LAGts evolve through time, this can affect the relative learnability of languages.

Figure 13 summarizes crucial options in the simulation giving typical values used in the experiments reported below, Figure 14 shows the potential costs and benefits to a LAGt of each interaction, and Figure 15 the components used to define fitness functions. (For calculation of parsability only successfully parsed sentence

algorithms (see e.g. Holland, 1993, 1995). However, the simulation is not technically one as fitness is internal to each LAGt and generations overlap. Also this use of genetic algorithm techniques should not be confused with Clark (1992) and Clark and Roberts (1993) model of the parameter setting *procedure* as a genetic algorithm.

Variables	Typical Values	
Initial Population Size		32
Interaction Cycle	Av. Interactions/LAgt	15-65
Simulation Run	Int. Cycles	50-10k
Crossover Probability		0.9
Mutation Probability		0/0.05
Learning	memory limited	yes
	critical period	4 int.cycles
	(re)settable n	1/4
Migrations	lg distance	3
	per cycle	2
	not genetic	T

Figure 13: Typical Simulation Options

1. Generate cost: 1 (GC)
2. Generate subset language cost: 1-3 (GSC)
3. Parse cost: 1 (PC)
4. Parse failure cost: 1 (PF)
5. Parse memory cost: WML(st)
6. Parse/Generate success benefit: 1 (SI)
7. Parameter (re)set cost: 1 (PS)
8. Parameter (re)set success benefit: 1 (SPS)
9. Maximum (re)settable parameters: n (MSP)

Figure 14: Cost/Benefits per Interaction

types are utilized, hence parse failures (PF) are subtracted from the total number of parse interactions for a LAgt. Predefined constant weights are used to balance the selection pressure created by the individual elements of fitness functions.)

4 Preliminary Experiments

The computational model must have several properties to qualify as a useful simulation of the grammatical acquisition process and of the (co)evolution of language and of the LAD. Firstly, it must be clear that for the chosen grammar set, at least some acquisition procedures in the space of possibilities definable in terms of LAgts' p-settings, are able to learn these grammars given finite and feasible (positive) input. Secondly, learning LAgts should converge reliably on the homogeneous language of a population of adult LAgts to model language maintenance and the continuity of language communities. Thirdly, it should be clear that coordinated grammars will evolve at some point during simulation runs quasi-randomly initialized with a population of non-communicating LAgts. Otherwise the model does not provide an environment in which the emergence and maintenance of structured language and its learners is likely.

Fitness Components	
Communicative Performance:	$\frac{SI}{GC+PC}$
Expressiveness:	$\frac{GC}{GC+GSC}$
Learnability:	$\frac{1}{MSP} \times \frac{SPS}{PS}$
Parsability:	$\frac{PC-PF}{WML(s_1...s_n)}$
Full Fitness Function:	$w1(CP) \times w2(Exp.) \times w3(Lrn.) \times w4(Pars.)$

Figure 15: LAgt Fitness

4.1 Effectiveness of Acquisition Procedures

Four acquisition procedures were predefined on the basis of two initial p-settings, unset and default, and two variants of the basic procedure, incremental $n = 1$ and non-incremental $n = 4$. Unset learners were initialized with p-settings consistent with a minimal inherited CGUG consisting of application with the N and S atomic categories already present. All the remaining p-settings were genuine parameters for both learners. The unset learner was initialized with all these unset, whilst the default learner had default settings for the parameters **argorder**, **gendir**, **subjdir**, **v1** and **v2** which specify a minimal SVO right-branching grammar. The unset learner represents a ‘pure’ principles-and-parameters learner with innate knowledge of the noun-verb distinction and their (predicate-argument) mode of combination. The default learner is loosely modelled on Bickerton’s (1984) bioprogram hypothesis, representing, additionally, a language learner with a preference for SVO unmarked order and predominantly right-branching syntax.²² These initial p-settings were combined with two acquisition procedures. One, n4, in which 4 parameters were updatable per trigger but updates were only retained if they resulted in a complete LF, and a second, i1, in which only one parameter could be updated per trigger but the updated value was retained if it resulted in recovery of more of the LF.

Each variant learner was tested against an adult LAgt initialized to generate one of seven full languages in the set which are close to an attested language; namely, “English” (SVO, predominantly right-branching), “Welsh” (SVOv1, mixed order), “Malagasy” (VOS, right-branching), “Tagalog” (VSO, right-branching), “Japanese” (SOV, left-branching), “German” (SOVv2, predominantly right-branching), “Hixkaryana” (OVS, mixed order), and a hypothetical OSV language with left-branching phrasal syntax. In these tests, a single learner interacted with a single adult, in which the adult always randomly generated a sentence type and the learner always attempted to parse and learn from it. The first figure in Table 1 shows the mean number of triggers (i.e. number of input sentences) required by the four learners to converge on each of the eight languages. The figure in brackets shows the mean number of triggers required for convergence when memory load was used to filter the learners’ access to triggers in accordance with the ‘starting small’ hypothesis (see section 1.1). These figures are each calculated from 1000 trials and rounded down to the nearest integer. When no memory constraints were imposed, each learner converged with less than a 1% error rate, to the target grammar on the basis of 100 random presentations of trigger sentences. 200 trigger sentences were

²²Lightfoot 1992:174f argues that the evidence from the pidgin-creole transition only supports a strictly weaker position than that of Bickerton (1994) in which some parameters have unmarked settings that are retained during language acquisition in the absence of robust positive evidence for a marked setting. Lightfoot’s weaker version of the bioprogram hypothesis is the one embodied in the SVO learner (modulo his discussion of Berbice Dutch) as this learner simply has more unmarked default parameter settings than the unset learner, and no ‘special’ mechanisms for acquisition which take over in the pidgin context.

Learner	Language							
	SVO	SVO _{v1}	VOS	VSO	SOV	SOV _{v2}	OVS	OSV
Unset (n4)	26 (32)	26 (31)	18 (26)	18 (25)	18 (25)	27 (33)	27 (30)	17 (20)
Default (n4)	14 (26)	17 (24)	16 (24)	17 (25)	15 (23)	15 (25)	18 (26)	26 (27)
Unset (i1)	32 (98)	30 (82)	30 (89)	31 (84)	31 (78)	31 (97)	31 (84)	31 (45)
Default (i1)	29 (93)	28 (72)	30 (74)	30 (73)	30 (70)	28 (89)	30 (73)	31 (49)

Table 1: Effectiveness of Four Acquisition Procedures

required to achieve convergence with this reliability when memory constraints were imposed. Thus, we can conclude with reasonable confidence that all these learners will converge for the languages tested, given this distribution and amount of data, with $p \geq 0.99$. (See Niyogi and Berwick, 1996 for detailed discussion of high-probability convergence from finite data.)

These results suggest that, in general, the default learners are more effective than the unset learners, though the difference is small and possibly insignificant for the incremental learner. For the OVS language (OVS represents 1.24% of the world’s languages; Tomlin, 1986), for the unattested or very rare OSV language, and for SOV_{v2}, the default (SVO) n4 learner appears less effective. In memory-constrained learning, learners pass through 4 maturational stages at each of which the allowable memory load during parsing is increased, and 25% of the triggers are presented at each stage. Unsurprisingly, given that the acquisition procedures are consistent, memory-based filtering of triggers does not affect convergence. However, it does slow it down since more triggers are required at each stage to ensure the learner has a high chance of being exposed to a convergent set of triggers overall. The variable performance of the different learners on the various languages suggests that many, perhaps intuitively unimportant, aspects of an acquisition procedure can affect its performance on a specific language, and consequent predictions concerning the relative learnability of languages.

Many other variant procedures result in effective learners for some or all of the eight languages tested, given varying amounts of triggering data. Testing the above learners on randomly-generated full languages suggests that these learners are capable of converging on any language in the set defined in the simulation. However, stronger conclusions would require either exhaustive experimentation or development of a formal proof of convergence (see Gibson and Wexler, 1994; Niyogi and Berwick, 1996; Osherson *et al.*, 1986).

4.2 Language Maintenance

The simulation employs random interactions within a population, some of whom will be learners. Thus, a proportion will involve learning LAgts interacting with each other or generating input for adult LAgts, before they have converged on the target language. Even in an initially homogeneous adult LAgts environment with a critical period for learning, if the proportion of learners to adults in the population becomes too high, the learners will not converge to the target language as the distribution of sentence types becomes more skewed towards those of subset languages. Two series of 50 interaction cycle simulations were run each initialized with either 32 adult unset n4 learners or 32 adult default n4 learners all speaking one of the eight languages described above. LAgts reproduced (without mutation) and died as described in section 3. However, given the p-settings of the initial population, LAgts were only able to reproduce further unset or default learners

or hybrid learners generated via crossover of these two acquisition strategies. In one series, memory limitations in learning was a factor and each interaction cycle consisted of a mean of 65 interactions per LAgT. In the other, memory limitations was not a factor and a mean of 25 interactions per cycle was used. Each condition was run 10 times.²³

In all the runs, the population continued to speak the original language and learners reliably converged to that language by adulthood. Thus, any (non-target) subset language speakers in the population at the end of an interaction cycle were, without exception, learners. In these runs, the proportion of adults never fell below 60%, and the levels of reproduction and death relative to population size were tuned to ensure language maintenance. Briscoe (1998b) gives further details of experiments to test and tune the (potential) stability of the simulation model. At first sight, the property of language maintenance or stasis may seem somewhat contradictory for an evolutionary model. However, it is critical that the model possess the *potential* to be stable (once all/most genetic and/or linguistic variation is removed) if it is to represent a plausible model of language acquisition and development. Though very occasional misconvergence during learning in ideal (i.e. homogeneous) conditions is probably possible, few would argue that this *alone* is the source of language change. Rather most linguistic change is probably a consequence of variation introduced through contact between language communities (e.g. Milroy, 1992), and the consequent linguistically heterogeneous data supplied to the learner. This is true even for those researchers who argue that language acquisition is the *engine* of change (e.g. Kroch and Taylor, 1997).

4.3 Emergence of Structured Language and its Learners

To explore the emergence and persistence of structured language (and consequently the emergence of effective learners) in the simulation model (pseudo) random initialization was used. A series of simulation runs of 500 cycles (approximately 125 generations of LAgTs) were performed with random initialization of 32 LAgTs' p-settings for any combination of p-setting values, with a probability of 0.25 that a setting would be an absolute principle, and 0.75 a parameter with unbiased allocation for default or unset parameters and for values of all settings. All LAgTs were initialized to be age 1, memory-limited n4 learners with a critical period of 4 interaction cycles, a maximum age of 10, and the ability to reproduce by crossover (0.9 probability) and mutation (0.05 probability) from 4-10. The full fitness function defined in section 3 was utilized. In around 5% of the runs, language(s) emerged and persisted to the end of the run.

Languages with close to optimal parsability typically came to dominate the population quite rapidly. However, sometimes less parsable languages were initially selected, and occasionally these persisted despite the later appearance of a more optimal language (but with few speakers). Typically, a minimal subset language dominated – although full and intermediate languages did appear briefly, they did not survive against less expressive but more easily learnable and parsable subset languages. Figure 16 is a typical plot of the emergence (and extinction) of language variants in one of these runs. In this run, around 10 of the initial population converged on a minimal OVS language and 3 others on a VOS language. The latter is more parsable / learnable and both are of equal expressiveness so, as expected, the VOS language acquired more LAgTs over the next few cycles. A few LAgTs also converged on VOS-N, a more expressive but less easily parsable extension

²³In these and subsequent experiments reported in this paper, the relevant results were observed in all runs (and others not discussed), so no statistical analysis beyond means is reported. The use of standard deviations, error bars and/or tests of significance would only be informative if results were less clearcut.

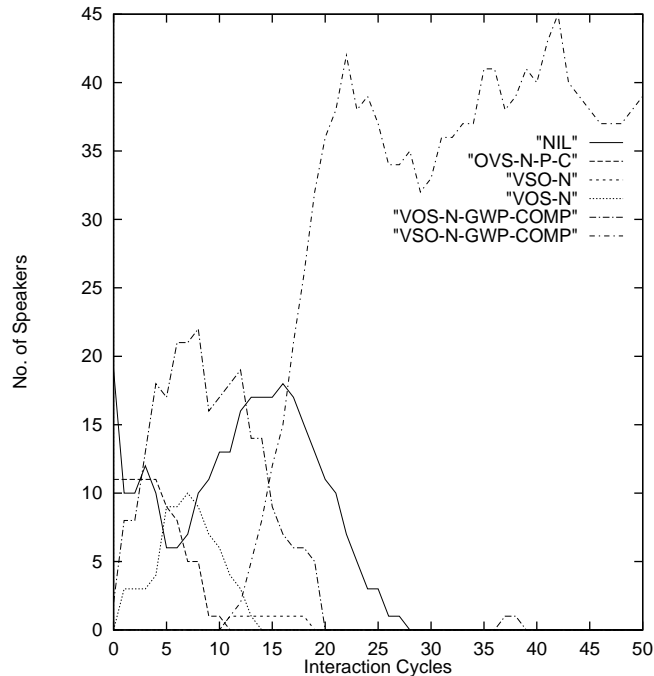


Figure 16: Emergence of language(s)

of VSO-N-GWP-COMP.²⁴ However, neither this nor the OVS language survived beyond cycle 14. Instead a VSO language emerged at cycle 10, which has the same minimal expressiveness of the VOS language but is more parsable, and this language dominated rapidly and eclipsed all others by cycle 40. Figure 17 is a plot of the mean fitness of LAGts through this entire run.²⁵ As can be seen, fitness improves rapidly early in the run, once a single dominant language emerges. Subsequent downward fluctuations are mostly caused by the occasional re-emergence of a few non-speaking LAGts who fail to learn the language, and upward fluctuations by a lower proportion of learners in the population, or by the increased use of a more parsable / learnable language.

As full languages did not emerge in these runs, a second identical set of 10 runs was undertaken, except that the initial population now contained 2 SOVv2 “German” speaking unset learner LAGts. In 7 of these runs, the population fixed on a full SOVv2 language, 2 on the intermediate subset language SOVv2-N, and 1 on the minimal subset language SOVv2-N-GWP-COMP. These runs suggest that if a full language defines the environment of adaptation then a population of randomly initialized LAGts is more likely to converge on a (related) full language. Thus, although the simulation does not model the development of expressiveness well, it does appear that it can model the emergence of effective acquisition procedures for (some) full languages. The pattern of language emergence and extinction followed

²⁴The names for languages are intended to be mnemonic: the first element indicates basic constituent order, the remaining elements delimited by ‘-/+', say what (un)marked features were absent / present from the associated grammar. For example ‘-N’ indicates no complex multiword NPs, -GWP indicates no permutation operation, and so forth. NIL represents speakers of no language.

²⁵Mean fitness is a measure in the range 0-1 combining mean communicative success, and mean LAGt learning costs (learnability), memory load (parsability) and subset language costs (expressiveness) – see section 3 above).

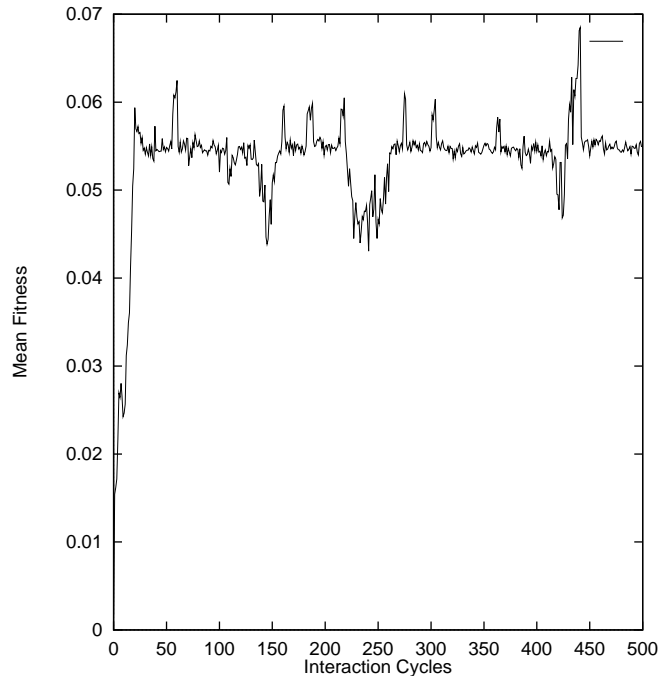


Figure 17: Mean fitness with language emergence

that of the previous series of runs: more parsable languages were selected from those that emerged during the run. However, often the initial locally optimal SOVv2 itself was lost before enough LAGts evolved capable of learning this language. The mean fitness and communicative success measures show very similar patterns to that of the previous runs. However, learning rates are worse, reflecting the more complex linguistic environment. There are clear changes in the percentages of absolute, default or unset p-settings in the population: the mean number of absolute principles declined by 6.1% and unset parameters by 17.8%, so the number of default parameters rose by 23.9% on average between the beginning and end of the 10 runs. This contrasts with the previous series of runs in which there was a greater increase in absolute principles than increase in default parameters. This may also reflect the more complex linguistic environment, in which (incorrect) absolute settings are more likely to handicap, rather than simply be irrelevant to, the performance of the LAGt.

These experiments demonstrate linguistic selection, chiefly for more parsable / learnable languages, and natural selection for LAGts with initial p-settings supporting effective language learning. They also suggest coevolution is occurring: there is a clear preference for absolute principles or default parameters over unset parameters. Unset parameters represent the least informative p-setting, whilst both default parameters and absolute principles provide more information about the linguistic environment. The preference for default parameters over absolute principles in the environment of one or more complex (full) languages may reflect the fact that in these simulations a dominant language is emerging as acquisition procedures are evolving, so flexibility is selected over further attenuation of the acquisition procedure in the absence of a constant and homogeneous linguistic environment. The experiments reported in subsequent sections investigate each of these results independently and in more depth.

5 Linguistic Selection

Selection for grammars and thus languages might occur as a consequence both of acquisition procedures and of the conflicting preferences for more parsable and more expressive languages. In the simulations discussed in the previous section, selection for more parsable / learnable languages occurred (although in some cases a more optimal language did not survive because it was spoken by too few speakers). But, it is not possible to definitely say whether it is parsability, properties of the acquisition procedure, or the proportion of speakers which is the causal factor in any given case. It is not even clear what precise form of the acquisition procedure is being deployed at any point in the randomly-initialized populations.

5.1 Linguistic Selection between Language Pairs

In more circumscribed experiments, linguistic selection for more parsable and/or more learnable languages, and the interplay between these two pressures as well as the ‘robustness’ of critical triggers, can be demonstrated directly. A series of 300 cycle simulations was run in which a population of 32 LAgts was initialized with differing proportions of unset n4 learner adult LAgts speaking two different full languages which contrasted in learnability and/or parsability. There were no differences in the initial p-settings in the population and mutation was not enabled. All conditions were run 10 times.

In one such series of experiments, the population was initialized with speakers of “German”, SOVv2, and “German with postpositions”, SOVv2+Pleft. These languages differ only in one directional parameter setting. There is no inherent learnability advantage, in terms of numbers of parameters to be set, for either variant given the unset learner. However, there is a small difference in the parsability of the two languages according to the WML metric (as Hawkins (1994) also predicts) with a preference for the more consistently right-branching phrasal syntax of “German”. Utilizing the full fitness function but no memory limitations during learning, and initializing with equal numbers of speakers of each variant, the population selected one or other variant within a mean 143 interaction cycles. The variant selected was dominated by the random factors in the simulation – principally how many learning LAgts happened to be exposed to a critical post/pre-positional trigger in a cycle of interactions. Figure 18 shows a typical run in which SOVv2 happens to emerge as the dominant language around cycle 260. When the proportion of postpositional speakers was reduced to one third of the initial population, then in two-thirds of the runs “German” emerged as the dominant language. When this proportion was further reduced to one fifth of the initial population, then “German” became dominant (within about 50 cycles) in all the runs. Figure 19 shows a typical run in which there is clear selection for SOVv2 as the initial frequency of the postpositional triggers is too low for this variant to gain enough of a foothold. Inverting these experiments so that the frequency of prepositional triggers is progressively lower does not produce a symmetric effect. It is only when less than one-tenth of the initial population are producing such triggers that selection of the postpositional variant occurs in all runs.²⁶

²⁶In an evolutionary model, random drift alone with no selection will (eventually) lead to the eradication of variation. This effect is well known in population genetics and can be analyzed probabilistically under certain assumptions about population size and the distribution of offspring within the population (e.g. Maynard Smith, 1998:25f; Roughgarden, 1979). The upshot is that for small finite populations fixation on a linguistic variant by random drift can be expected to occur within $2N$ interaction cycles with a standard error a little greater than N , where N is population size. As the population in these simulations initialized with 32 LAgts typically rises to around 60 quite quickly and then stabilizes, consistent fixation within 50 interaction cycles in 10 runs constitutes reliable evidence of linguistic selection.

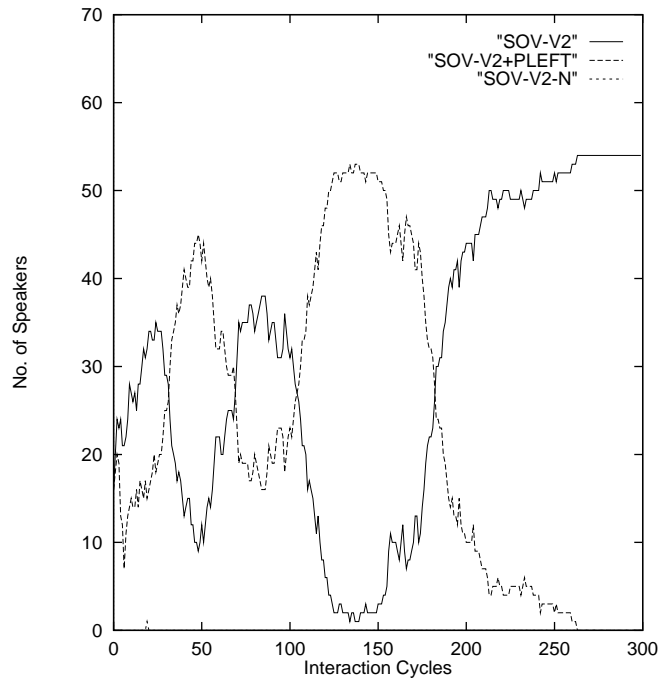


Figure 18: Random selection

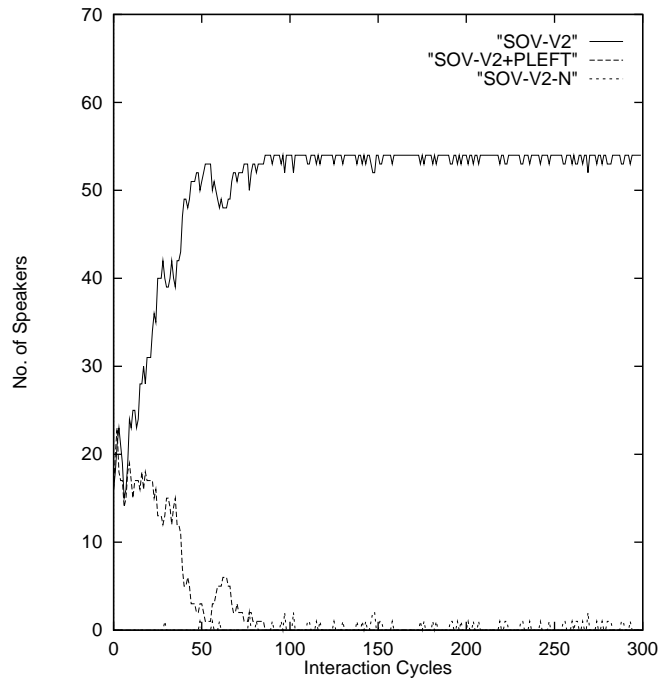


Figure 19: Linguistic selection

These runs show that general parsability factors for both adults and learners can militate (weakly) against a variant form by reducing the fitness of LAGts employing that form. This general explanation for linguistic selection has been questioned though, since it relates parsability directly to LAGt fitness. Lightfoot (1991) and others have argued that it is unlikely that *specific* properties of a language spoken by speakers would lead directly to increased numbers of offspring. It might be more plausible to argue that such properties might lead indirectly to increased offspring by increasing communicative success. Such an indirect effect could easily be incorporated into the simulation model by positing that the probability of successful interaction is partly a function of the working memory load created by the sentence type chosen. An alternative assumption is that maturational working memory limitations will decrease the chances of less parsable sentence types functioning as effective triggers (see e.g. Kirby, 1996, 1997, 1998 for a similar position). To simulate this scenario, the same set of runs was done with random selection for LAGts but with memory limitations during learning. The results show a very similar pattern to those reported above, though the selection effect is weaker and it is only when the proportion of initial postpositional speakers is less than one sixth that the prepositional language dominates reliably. A final variant of this experiment is to assume initially equal numbers of speakers of each variant but weight the production of sentence types by their parsability, under the assumption that speakers avoid less parsable sentence types, perhaps to improve their chances of communicative success (e.g. Hawkins, 1994:180f). Altering the LAGts' generation algorithm so that sentences selected with WMLs above 40 have a less than 100% chance of being uttered, falling from 80% for a WML over 40 to 20% for WMLs over 200, ensured that in all runs the population converged on SOVv2. Therefore, the simulation model predicts that, given any assumptions allowing an effect of parsability on language learning, production and/or interpretation, parsability will cause linguistic selection.²⁷

The interplay between parsability and learnability can be seen in simulation runs initialized with equal numbers of "German", SOVv2, and "Japanese", SOV, speakers. SOVv2 has a slightly lower mean WML, and thus parsability, than SOV (largely because the freer constituent ordering options of Japanese relative to German are not modelled effectively in "Japanese" (see e.g. Hawkins, 1994)). Figure 20 shows the languages which emerge during one run with the full fitness function. SOVv2 comes to dominate the population after 5 interaction cycles. The other language which persists, SOVv2-N, is a subset language spoken by learners of SOVv2. SOVv2-GWP-COMP is also a subset language of SOVv2 so the 'recurrence' of this language at cycle 45 just reflects presence of one or two less successful learners at the end of an interaction cycle. The other non-v2 languages are eliminated within the first 5 interaction cycles. All runs exhibited the same clear effect. However, with parsability not a factor in LAGt fitness, the opposite result was obtained – in all runs SOV came to dominate with SOV-N(-GWP-COMP) subset languages, again spoken exclusively by learners. As SOV is consistently selected in all such runs when parsability is not a factor, this is most likely to be because SOVv2 requires the setting of the v2 parameter and mixed clausal / phrasal ordering parameters, reflected in the greater number of triggers required for convergence in Table 1. Thus, in the case of these two languages, ease of parsability for both learners and users creates greater overall linguistic selection pressure than that created by the other

²⁷Caution should be used when making inferences from these results concerning the frequency thresholds of the postpositional trigger. A different and probably more plausible learning algorithm which 'damped' response to an initial trigger and tracked the relative frequencies of conflicting triggers in the input before finally setting a parameter (e.g. Kroch, 1991; Niyogi and Berwick, 1997b) would make different predictions, though the basic conclusion concerning linguistic selection would still hold.

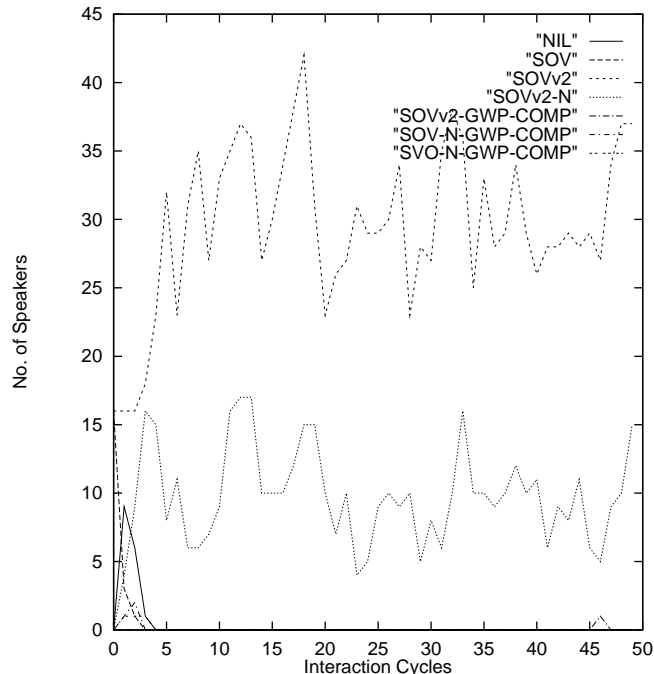


Figure 20: Selection for SOVv2 over SOV

requirements of learnability.

5.2 Linguistic Selection with Migrations

To demonstrate more general linguistic selection for more (locally) optimal grammars / languages, a number of experiments were undertaken with p-setting invariant populations of LAgts operating in a continuously heterogeneous linguistic environment, providing the variation on which linguistic selection could work. Migrations of adult LAgts speaking a different language, whenever the population was close to convergence on a single language, ensured heterogeneity. Language change occurs when learners converge preferentially on one or other language, or a mixture, or a subset, whilst exposed to data from more than one source grammar. There is also an increased possibility of misconvergence to a grammar not directly exemplified in the adult population when the (uniform) distribution of triggers from a single source is skewed by the presence of several sources. This is particularly true for parameters with default initial settings.

In this series of experiments, approximately one third additional adults were added to the population at regular intervals, all speaking the same new full language to ensure that the new language had a reasonable chance of surviving a number of cycles and thus influencing learners. LAgts added in this fashion had identical initial p-setting configurations as the existing population, so no genetic variation resulted. The maximal ‘distance’ between an existing dominant language and the new language was three parameters. ‘Migrations’ of this type occurred every other cycle provided that a clearly dominant language had emerged at the end of the previous cycle. Thus, migrations ensure a constant source of linguistic heterogeneity throughout a simulation run. The amount of variation introduced was tuned to the maximum consistent with the population maintaining a mean communicative

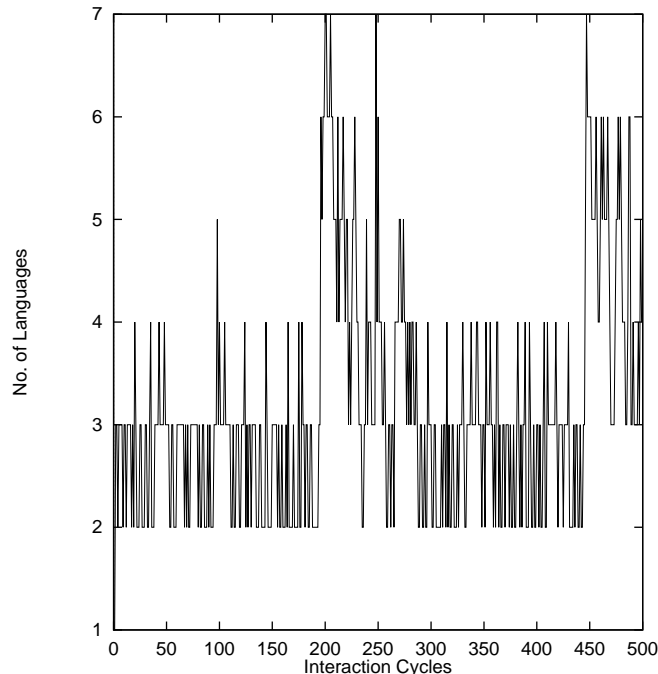


Figure 21: Number of languages in a typical run with migrations

success level of 90% or better. After the first interaction cycle in all runs with migrations there are always two or more language variants present in the linguistic environment at any one time. Figure 21 plots the number of languages in the run using the full fitness function discussed below (which is also typical for the other conditions discussed).

In the first set of experiments, no fitness function was utilized, 500 cycle runs were used, and all LAgts were unset n4 learners, as defined in section 4.1. LAgts reproduced randomly with no regard for communicative success or the nature of the language they utilized. However, because all LAgts were using an effective acquisition procedure, because the simulation was initialized with a single full language, and because the amount of linguistic variation was controlled, in all runs communicative success averaged over 90%. This is plotted in Figure 22 for a typical run – dips correspond to points where migrations occurred. The overall mean costs of the languages adopted by the population were reduced during the course of this and other runs via linguistic selection for learnability, as illustrated in Figure 23. The figure plots an integrated measure for the mean learnability, parsability and expressiveness of the languages present in each interaction cycle, and also breaks this down into the three components, so it can be seen clearly that the population is optimizing learnability at the expense of expressiveness. In this and other runs with random LAgts selection, the population selected subset languages, which are less expressive but more easily learnable, as they require fewer parameters set. As memory load plays a role in learnability via the filtering of triggers, often, but not in every case, parsability was also selected for. Similar results were obtained from all ten runs.

These results confirm that linguistic selection can occur without any *natural* selection for LAgts whatsoever. The bias of the acquisition procedure which the LAgts use is enough to create a process of selection for the most learnable lan-

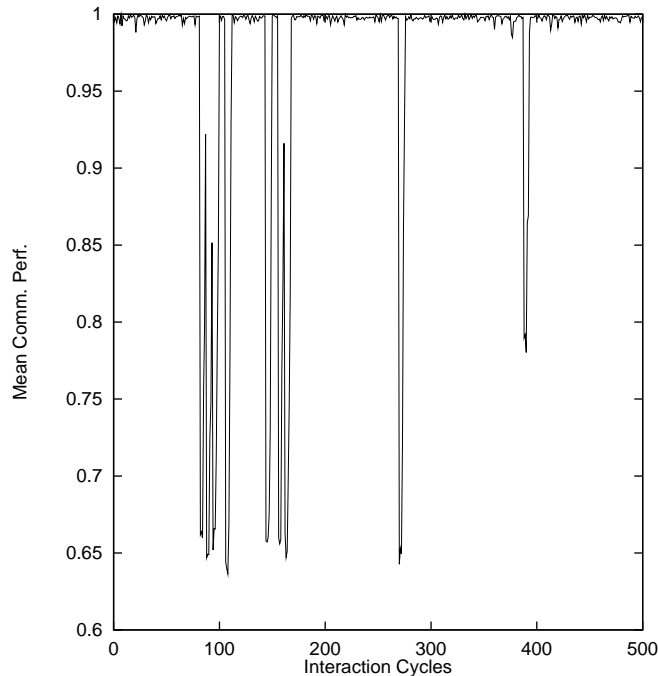


Figure 22: Communicative success with random selection and migrations

guages. Kirby (1996, 1997, 1998) explores in detail this form of linguistic selection as languages, or more accurately triggers, pass repeatedly through the ‘bottleneck’ of language acquisition. Essentially, triggers compete for learners and those which are more able to pass through the filter of the acquisition procedure will set more parameters in more learners. In this way languages will over time adapt to the language acquisition procedure. Kirby argues that, on the assumption that parsability is *identical* to learnability, languages will, therefore, evolve to be optimally parsable, and demonstrates that this form of linguistic selection may explain statistical constituent order universals without the need for any natural selection for LAgts.²⁸ One weakness of this position is that Kirby only models differential learning between competing variants. Once a more complete acquisition procedure is defined, the possibility of simply *not* learning arises, and thus the possibility of converging on a subset language. This is exactly what is seen in runs of the simulation model without natural selection for LAgts – there is no pressure for LAgts to prefer a more expressive, and thus costly, language, so, even if the population is initialized to use such a language, the community soon selects for subset languages. A counteracting pressure for expressiveness is needed to prevent this tendency.

Other runs were performed using communicative success, parsability, expressiveness and/or learnability as components of the fitness function on LAgT reproduction. In the runs where expressiveness was a component of selection, the population did not converge on subset languages despite the linguistic variation in the learning environment created by migrations. When the full fitness function was utilized, LAgts’ mean fitness typically did not vary greatly, except where migrations removed them temporarily from a (local) optimum. The mean language costs for parsability, learn-

²⁸Briscoe (1998b) discusses Kirby’s work in more detail. In the model described here, learnability involves other factors than parsability, but also parsability can be a factor in more general communicative success (see section 5.1) creating other routes for linguistic selection.

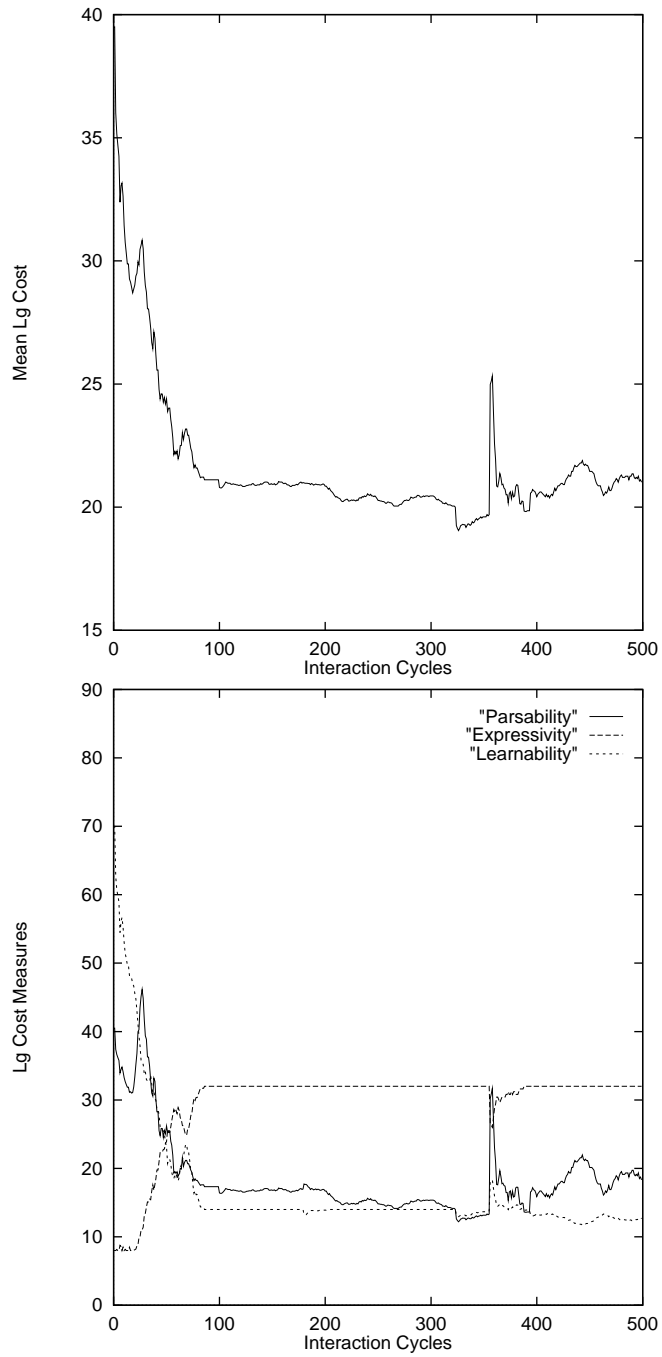


Figure 23: Language costs with random selection and migrations

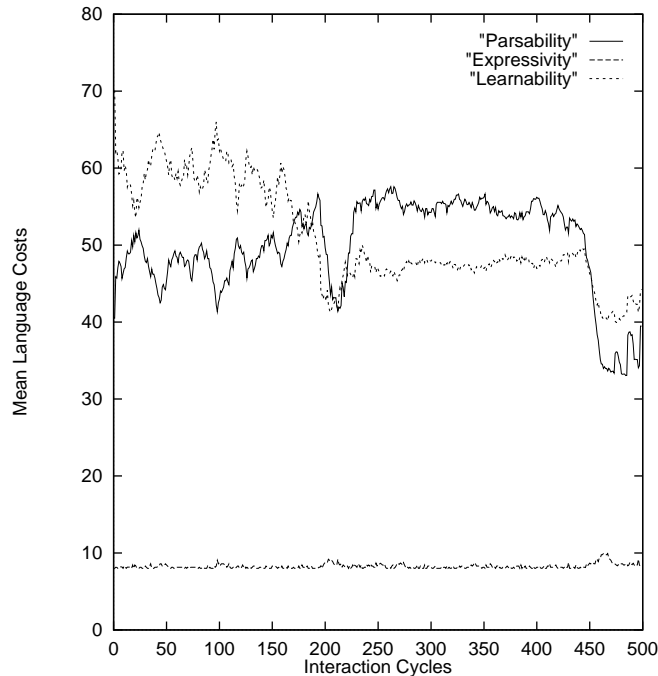


Figure 24: Language costs with natural selection and migrations

ability and expressiveness displayed in Figure 24 demonstrate consistent linguistic selection for more easily learnable and parsable full languages. This is typical of such runs where the full fitness function is utilized.²⁹ Comparing this with Figure 23 above demonstrates the contrast with linguistic selection without natural selection.

The experiments reported in this section demonstrate that linguistic selection occurs whenever there is linguistic variability under a wide range of different possible assumptions about the precise impact of learnability, parsability, expressiveness, and communicative success. However, in these experiments, the acquisition procedure has been held constant. The next section explores the effect of natural selection amongst variant acquisition procedures.

6 Natural Selection

The following experiments explore the relative efficiency of several variant acquisition procedures on a range of full languages, by holding the linguistic environment constant but allowing natural selection between variant acquisition procedures to occur. The role of memory limitations in learning is also explored. The experiments provide the background for exploring the coevolutionary dynamic between linguistic

²⁹In some cases, migrations still cause the population to settle on a less optimal language, though this is far less frequent with natural selection for LAGts. The use of random interaction between LAGts idealizes a vast range of sociolinguistic factors which influence selection between linguistic variants, such as the prestige, charisma, economic power or ideology of the speakers of the variants, and so forth. In reality, these factors probably significantly outweigh considerations of selection for parsability or learnability in many situations; for example, where the migrants are conquering invaders. In addition, the simulation does not address differences in death rates between linguistic groups due to disease, genocide, and so forth. Dixon (1997) and Pullum (1981) provide an extended discussion of such factors.

selection amongst variant languages and natural selection from variant acquisition procedures.

6.1 Evolution of Acquisition Procedures

A series of 300 interaction cycle runs were performed in which the population was initialized with 16 unset and 16 (SVO) default learners, as defined in section 3. All the initial population were adults speaking one of six full languages. They were either all incremental learners able to update one parameter per trigger or all non-incremental learners able to update 4 parameters per trigger. There was no mutation, so natural selection was only able to select between the five initial parameter settings which distinguish the unset from default learners. Crossover alone cannot change the initial default value of a parameter, only its status as default or unset so the question being explored is under what conditions default parameters, with the default values specified by the default (SVO) learner of section 3, would be retained in preference to unset versions of these parameters. In all runs, the full fitness function was used, but all conditions were run with and without maturational memory limitations during learning.³⁰

The results of these experiments demonstrate marked interacting effects of language type, acquisition procedure and memory limitations on the propensity for specific default initial parameter settings to go to fixation. Table 2 shows the percentage of simulation runs under the varying conditions for which default-valued parameters went to fixation in the population within 300 interaction cycles. For example, with the non-incremental memory-limited acquisition procedure applied to “English”, SVO, the Arg0 parameter was default-valued for every member of the population by the end of 80% of runs. On the other hand, with the incremental memory-limited learner Arg0 fixated to a default parameter in only 10% of runs. Thus, in 20% of runs with the non-incremental learner and 90% of runs with the incremental learner, an unset version of Arg0 went to fixation in the population.³¹ The figure in brackets after each percentage indicates the mean number of interaction cycles to fixation for each condition. In similar experiments with random selection of LAGts, this mean across all conditions was 139, which gives an estimate of the average time taken to fixation under random drift. Thus, mean fixation times of 50 cycles or less with a strong bias (say, $\geq 80\%$ or $\leq 20\%$) towards either type of parameter constitute reasonable evidence of consistent selection pressure. However, either a strong bias coupled with a higher mean fixation time or lack of a strong bias, even with a lower fixation time, cannot be considered reliable evidence.

If we consider the subject direction parameter (**subjdir**) with and the non-incremental memory-constrained learner (n4+ml), we can see that there appears to be quite strong selection pressure in favour of the default initial (leftward) setting when learning SVO, VOS or SVOv1, weaker pressure for VSO and SOV and either very weak or no pressure for SOVv2. Similar interactions with language are in evidence with the other parameters and acquisition procedures. On the other hand, this pressure for a default initial value for **subjdir**, and other parameters, is generally reduced or gone when the non-incremental learner is not memory-constrained, as can be seen from the generally higher fixation times and lower percentages. With

³⁰Similar results in most runs would be obtained by running the same experiments with a fitness function based purely on communicative success, or communicative success and learning cost, because the effects of expressiveness and parsability are rendered negligible by the linguistically homogeneous environment. However, some form of natural selection for LAGts is required in order to preclude simple random drift amongst variant acquisition procedures (which, given enough variation, invariably results in loss of language in the population).

³¹In about 2% of cases, specific parameters did not go to fixation for either type and the population retained variation. In these cases, the percentage count assigned to default-valued parameters was halved in Table 2

Learner	Language					
	SVO	SVO _{v1}	VOS	VSO	SOV	SOV _{v2}
n4+ML						
arg0	80% (29)	80% (26)	50% (29)	60% (39)	50% (41)	70% (44)
gendir	80% (30)	90% (23)	50% (30)	60% (61)	50% (36)	80% (54)
subjdir	90% (28)	80% (30)	100% (32)	80% (58)	80% (64)	80% (111)
v1	40% (70)	90% (53)	100% (62)	90% (54)	90% (56)	100% (55)
v2	40% (41)	90% (53)	100% (50)	90% (76)	90% (50)	100% (67)
n4-ML						
arg0	80% (40)	100% (19)	90% (30)	90% (31)	80% (43)	80% (41)
gendir	80% (38)	100% (19)	90% (30)	80% (41)	80% (39)	90% (35)
subjdir	80% (33)	80% (43)	100% (28)	70% (63)	50% (59)	95% (99)
v1	30% (40)	90% (50)	95% (88)	90% (55)	50% (57)	100% (55)
v2	35% (77)	90% (48)	100% (59)	90% (88)	50% (68)	100% (51)
i1+ML						
arg0	10% (25)	50% (23)	20% (24)	20% (35)	30% (30)	10% (23)
gendir	10% (22)	60% (33)	30% (27)	20% (43)	30% (32)	20% (27)
subjdir	10% (22)	50% (32)	60% (27)	20% (43)	60% (63)	0% (27)
v1	10% (22)	75% (33)	20% (27)	20% (43)	10% (102)	0% (27)
v2	0% (37)	60% (150)	30% (63)	10% (49)	0% (49)	0% (36)
i1-ML						
arg0	30% (28)	20% (29)	0% (33)	40% (22)	50% (32)	40% (34)
gendir	40% (48)	60% (32)	0% (40)	20% (42)	50% (38)	40% (35)
subjdir	30% (48)	20% (33)	0% (40)	40% (42)	80% (38)	40% (35)
v1	10% (48)	50% (33)	60% (40)	20% (42)	35% (38)	30% (35)
v2	20% (120)	45% (174)	40% (150)	20% (131)	35% (113)	40% (236)

Table 2: Percentage of Default-Valued Parameters and Mean Fixation Times

the incremental learner there appears to be no consistent pressure for either type of initial value, especially without memory constraints; or an opposite pressure for an unset initial value, as with **subjdir** and **i1+ml** learning SVO, for example.

The trend in favour of default values with the non-incremental learner is what we would predict, given the results summarized in Table 1 of section 4.1, which show that there is a greater efficiency gain with default initial settings for most of the languages tested for this acquisition procedure. The trend against some default settings with the incremental learner is not so predictable and underlines the need for this second type of experiment if the dynamics of such procedures are to be thoroughly explored. The effect of maturational memory limitations is to decrease fixation times and to (mostly) increase selection for default initial values, though this is far less clearcut with the incremental acquisition procedure.

These experiments are somewhat artificial because the range of variation available for selection amongst acquisition procedures is very constrained. Therefore, there is little to be gained by further (statistical) analysis of the results. Nevertheless, they demonstrate that the precise form of learner which emerges will be very dependent on the environment of adaptation. Whilst genetic assimilation may occur in a wide variety of scenarios, a SVO default learner is only likely to emerge in the presence of some and not other dominant languages, and may even require additional assumptions such as non-incremental memory-constrained learning.

7 Coevolution

The experiments of section 5 demonstrated evolution of language on a historical timescale within a genetically-invariant population of LAgts. Those of section 6 demonstrated evolution of acquisition procedures, within circumscribed limits, with maintenance of a single dominant language (see section 4.2). To demonstrate coevolution, it is necessary to allow the LAgT population to evolve and to allow a significant degree of language change in the same run. LAgts' initial p-settings were varied by allowing mutation of a single element of a LAgT p-setting (with probability 0.05) during LAgT reproduction. Successful variant initial settings could then propagate through the population via single-point crossover (with probability 0.9). This allowed much less circumscribed evolution of initial p-settings than in section 6. In addition, the parameter n which determined the number of updatable parameters per trigger could mutate by ± 1 with probability 0.05 during LAgT reproduction. The full fitness function was used.

7.1 Coevolution without Migrations

In the first series of such experiments, the initial population were all unset $n4$ learner adults speaking one of the clearly-attested full languages. Mutations can change a principle to a parameter or vice-versa, alter the type of a parameter, or flip the value of a principle or default parameter. Therefore, they could, in theory, introduce a language variant by altering the value of a principle or default parameter. However the degree of linguistic variation in such runs was typically minimal with populations sampling around 5 closely-related full languages over 500 interaction cycles.

In these runs, the populations always evolved towards initial p-settings which enhanced the learnability of the dominant language in the environment. Figure 25 shows mean LAgT fitness for one such population and also the relative proportions of default parameters, unset parameters and principles in the same population. In all such runs, the proportion of default parameters grew at the expense of unset ones, with default values reflecting the language of the environment. In addition, the mean number of updatable parameters per trigger fell until typically the whole

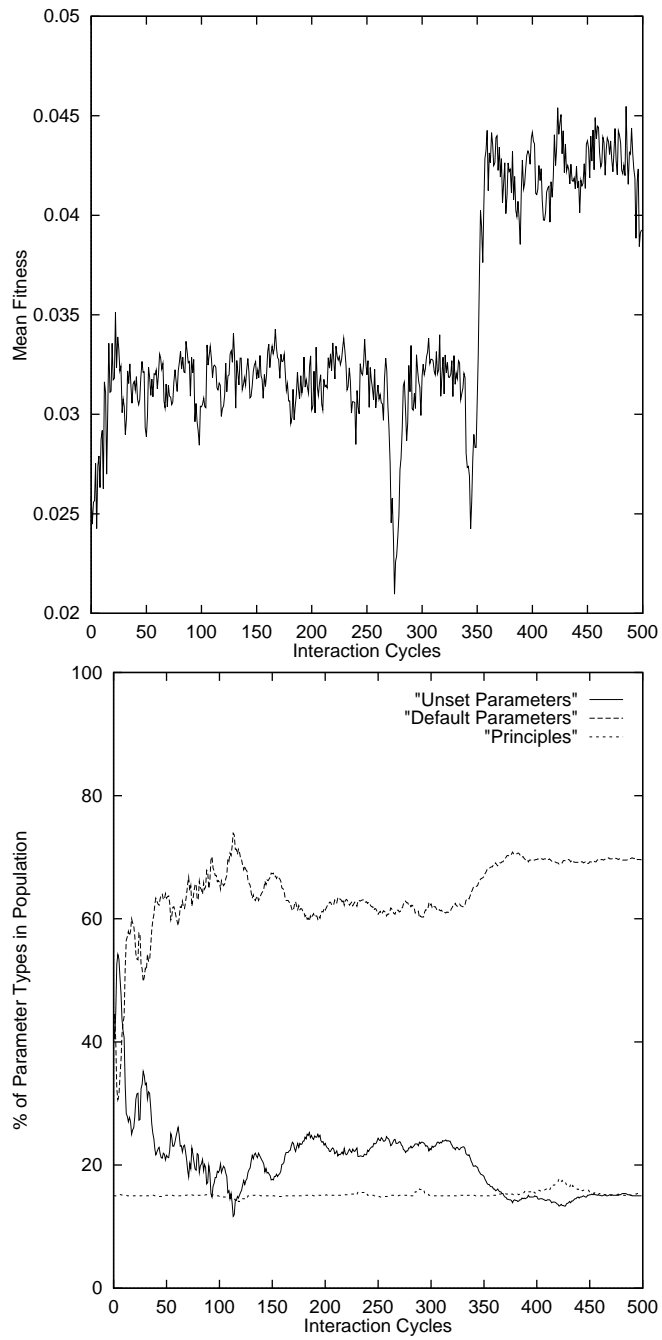


Figure 25: Mean fitness and p-setting types during coevolution without migrations

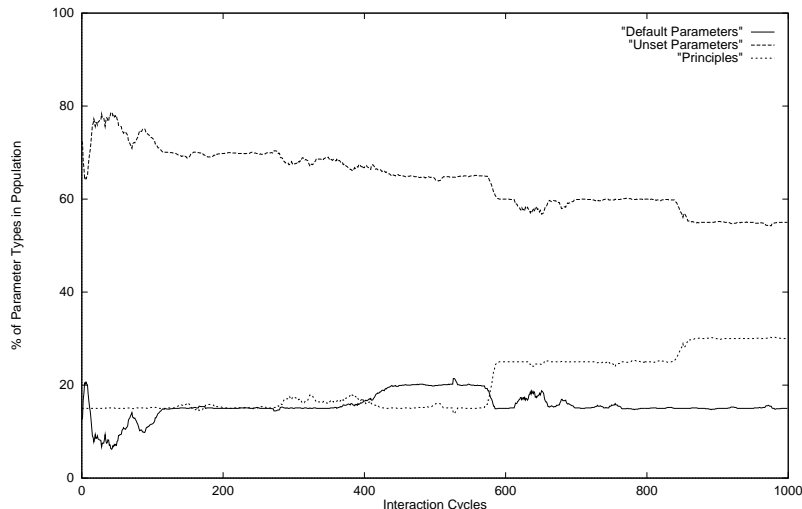


Figure 26: Percentage of p-setting types with migrations

population converged on a value of 2 or 3, depending on the dominant language. Consequently, LAg_t fitness improved over the course of the run as a result of reduction in learning costs, whilst mean parsability, expressiveness and communicative success remained roughly constant.

These results are clear evidence of genetic assimilation in which LAg_ts are evolving to be able to acquire the dominant language more effectively. Similar experiments with the *il* learner with maturational memory limitations showed similar, though less marked effects. By replacing unset with default parameters which have initial settings compatible with the dominant language, the LAD is evolving an accurate language-specific learning bias which simplifies the acquisition of this language. At the same time, this bias itself will alter the relative learnability of other languages. However, linguistic variation in these simulations is very limited, caused only by occasional failures of convergence, mutations of default parameter values or mutations of parameters to principles. Consequently, the rate of linguistic change is very slow, creating a fairly constant selection pressure for genetic assimilation to work on. As discussed in section 1.3, Deacon (1997) has argued that genetic assimilation will not occur because, in practice, languages change faster than mutations can go to fixation in a population.

7.2 Coevolution with Migrations

To see whether genetic assimilation would occur with maximal linguistic variation consonant with communicative success, a second series of experiments was run identical to those described above, except that migrations occurred as often as was compatible with mean 90% communicative success over the entire 1000 cycle run. Figure 26 shows the relative proportions of default parameters, unset parameters and principles for one such run with the population initialized to unset *n4* memory-constrained learners.

In these runs, LAg_ts still evolved LADs which improved learnability despite the fact that typically the dominant language changes about 20 times and approximately 50 languages are sampled by the population. However, as in the run shown, there was a greater tendency to replace unset parameters with principles rather than just

with default parameters. Over 10 such runs, the proportion of unset parameters always declined, by a mean 35% leading to around 50% of p-settings being principles or default parameters with roughly an equal number of new principles and default parameters. In other respects, results were identical to the first series of runs with LAgt fitness improving as a consequence of reduced learning cost. However, the greater degree of linguistic variation also allowed more linguistic selection for more optimal languages.

The replacement of unset parameters by principles is an example of the type of genetic assimilation which Pinker and Bloom (1990) envisage, in which the class of learnable languages is (further) constrained by the LAD in the interests of enhanced learnability. Thus, in these runs we see examples of genetic assimilation of both learning biases (defaults) and constraints (principles), albeit at a slower rate than when the linguistic environment was more constant. To see how long genetic assimilation would continue in a heterogeneous linguistic environment, several such simulations with migrations were run for 10,000 cycles. In these, the mean decline in the proportion of unset parameters was 55% with 65% of p-settings being principles or parameters at the end of the runs. Once again approximately half of the replaced unset parameters were default parameters. Plots of the proportions of each type of parameter show an asymptotic rate of genetic assimilation for default parameters and principles. Finally, in similar runs with populations initialized to reproduce learners with all default parameters with values appropriate to the initial language, the population invariably evolved away from such ‘total’ genetic assimilation towards p-settings containing some unset parameters. Therefore, we can conclude that there is an upper limit to genetic assimilation in the face of such linguistic variability.

7.3 Discussion

Why then is there (partial) genetic assimilation even in the face of great linguistic heterogeneity and rapid linguistic change? And why, when change is rapid, is there a greater tendency for the assimilation of principles as well as default initial parameter values? Firstly, consider the possible mutations which can occur within a p-setting and their expected fitness effects; Table 3 catalogues the possible transitions of individual initial p-settings (which can be created by a single mutation) and their expected fitness cost / benefit in terms of the ‘truth/falsity’ (T/F) of the resulting p-setting value in the current linguistic environment. The fitness cost / benefit is based on the expected effect on learnability. It is clear that any transition from a false principle (i.e. one which is inconsistent with the current linguistic environment) will incur a fitness benefit, because it will allow a LAgt a chance to learn the dominant language. By contrast, a transition from a true principle to anything other than a true default will have a learning cost because it will either render learning impossible or increase the number of parameters to be updated. Likewise, no transition from a true default creates any benefit and three incur a cost. Three transitions from a false default incur learning benefit, only a transition to a false principle incurs a cost, by making learning impossible. Transitions from unset parameters to true default parameters or true principles are beneficial, whilst a false principle, as always, incurs a (fatal) cost. The transition to a false default incurs no cost (or benefit) because during learning it still takes one parameter update to obtain the correct value.

It should be clear from this discussion, that what we would expect to evolve is a population with correct principles, predominantly correct default initial parameter values, and possibly a minority of unset and/or default incorrect parameters. In an unchanging linguistic environment, we would expect the population to eventually fix on all true principles or default parameters. However, in all the experiments reported above the linguistic environment is never entirely homogeneous or static.

Old		New		Expected Fitness
PS-Type	P-value	PS-Type	P-value	
Absol	F	Def	F	$f >$
Absol	F	Def	T	$f >$
Absol	F	Absol	T	$f >$
Absol	F	Unset	?	$f >$
Absol	T	Def	F	$f <$
Absol	T	Def	T	$f =$
Absol	T	Absol	F	$f <$
Absol	T	Unset	?	$f <$
Def	F	Absol	F	$f <$
Def	F	Absol	T	$f >$
Def	F	Def	T	$f >$
Def	F	Unset	?	$f =$
Def	T	Absol	F	$f <$
Def	T	Absol	T	$f =$
Def	T	Def	F	$f <$
Def	T	Unset	?	$f <$
Unset	?	Absol	T	$f >$
Unset	?	Absol	F	$f <$
Unset	?	Def	T	$f >$
Unset	?	Def	F	$f =$

Table 3: P-setting Transitions and Fitness Effects

Therefore, the ‘truth/falsity’ of a p-setting is an approximation: a value may be predominantly correct in the current environment given the dominant language, but become predominantly or completely incorrect over succeeding cycles (and vice versa). Whether an initially beneficial mutation achieves fixation, or even predominance, within the population will depend not only on the initial benefit it offers the mutated LAgT, but also on the continuing benefit to its descendents. It is here that coevolutionary effects will occur; for example, as a predominantly correct principle spreads through the population, it will create greatly increased linguistic selection for languages which obey this principle. This, in turn, will increase the chance that the principle will go to fixation in the population, rendering languages which do not obey the principle unlearnable. Similar reasoning applies to default-valued parameters.

In a changing environment, we might expect there to be a preference for default parameters over absolute principles, because an initially predominantly correct principle which spread through a proportion of the population would incur a high, possibly fatal, cost to them if it subsequently became (predominantly) incorrect. By contrast, a default parameter which becomes incorrect, incurs no more cost than an unset parameter, given the acquisition procedure assumed in the current simulation. There does appear to be a bias towards genetic assimilation of default parameters in the experiments reported above with lowish rates of linguistic change (see also section 4.3). The migration mechanism, used in the simulation for introducing linguistic variation, tends to reinforce the status of principles which have spread through more than 50% of the population and accelerate their fixation (because it introduces adults with identical initial p-settings to those of the existing majority). So, further experiments are needed to explore the degree of genetic assimilation of principles as opposed to default parameters using different migration

and learning mechanisms.

In the experiments reported above with mean 90% communicative success, the fastest observed rate of change from one dominant language variant to another was 4 interaction cycles. The fastest observed rate at which a mutation in a p-setting reached fixation was 43 cycles. This suggests that linguistic evolution of grammatical parameters was only about one order of magnitude faster than ‘genetic’ evolution of p-settings. Increasing the speed of linguistic change would have resulted in a decrease in communicative success below what is assumed reasonable in a language community. Nevertheless, the simulation tells us nothing about the true relative rates of linguistic and biological evolution – increasing the size of the population (in the simulation or real world) would, for example, slow down biological evolution. But, there can be no certainty about the size of the ancestor population in which the LAD evolved. Deacon (1997:329) suggests that linguistic evolution is ‘many’ orders of magnitude faster than biological evolution, arguing that languages can change their major grammatical properties over thousands of years (historically, 1-2 millennia for the types of constituent order properties modelled here). However, the time taken for a major grammatical change and the time taken for biological evolution will depend critically on population size, geographical dispersal, diffusion rates of genes and of variant grammatical forms, and so forth. In the simulation runs with rapid linguistic change, typically 2-3 major grammatical changes propagate through the population every 50 interaction cycles. Therefore, default parameters and absolute principles are being genetically assimilated and going to fixation in the population typically in the face of several such major linguistic changes.

The key to understanding why genetic assimilation is still likely to occur, almost regardless of the relative speed of change, is that the sample space of possible grammars and associated languages is vastly larger than the number of grammars which can be sampled by a population in the time taken for a principle or default parameter to go to fixation. In the simulation, there are under 300 languages and only 70 distinct full languages. Therefore, in the time taken for a p-setting to go to fixation typically around 5% of the space of grammars might be sampled. This means that 95% of the selection pressure for genetic assimilation of grammatical information remains constant at any one time. In his discussion, Deacon (1997:329f) ignores the issue of the space of grammatical possibilities and the degree to which this can be sampled in the time required for biological evolution. It is impossible to estimate the real size of this space properly, but few linguists would probably balk at the idea that 30 independent binary grammatical parameters will be required to capture the differences between the world’s languages in an account of universal grammar. Given this, there are billions of distinct grammars to explore. This guesstimate is based on the existence of an evolved LAD. Prior to the emergence of the LAD, the space of possible grammars would have been infinite. Rapid changes in the tiny subset of potential grammatical systems which the ancestral linguistic population was exposed to could not prevent genetic assimilation on the basis of the many potential systems which were *not* sampled; perhaps, for example, all those potential grammatical systems which would have resulted in arbitrarily intersecting dependencies between constituents (see section 1.3).

8 Conclusions and Further Work

The model of the LAD and of an LAg_t developed here extends work on grammatical acquisition in the parameter setting framework in several ways. Firstly, the partially-ordered parameter setting procedure described integrates a computationally tractable and psychologically feasible algorithm with a more detailed account of UG within the GCG framework. Secondly, this procedure has been shown to be

effective experimentally on a more complex grammar / language set than has been investigated in this framework hitherto. Thirdly, the effect of maturational memory limitations ('starting small') has been shown to be largely irrelevant to convergence for this class of consistent procedures. Fourthly, the criterion for retaining a parameter update has been shown to have marked effects on the overall behaviour of the acquisition procedure. Fifthly, the coevolutionary experiments suggest that the starting point of any acquisition procedure will not be arbitrary but will be informed to some extent by the environment of adaptation for the LAD. This latter conclusion is important in any assessment of the significance of learnability arguments which assume arbitrary initial parameter configurations. Finally, embedding the model of the LAD in a population of LAgts allows more precise study of predictions concerning language change, in a manner analogous to Niyogi and Berwick (1997a,b). Nevertheless, there are several ways in which this model of the LAD needs extending and such extensions might undermine some of the conclusions above. The current model does not account for noise or ambiguity of parameter expression in the input to the learner. Such extensions are currently being developed, but might turn out to be more sensitive to the effect of maturational memory limitations, for example.

In an answer to the question posed in section 1: how do often partially inaccurate language learning biases arise and how pervasive are they in language acquisition? The work reported suggests that genetic assimilation of information into the LAD on the basis of the dominant languages in the environment of adaptation provides a plausible answer. When LAgts' p-settings can vary, under all experimental conditions genetic assimilation of more 'informative' default parameters or absolute constraints occurs. The general effect of genetic assimilation will be to build in as much information concerning the linguistic environment as possible to make learning more efficient and robust. Thus, the idea that the LAD will incorporate bias in the form of initial default-valued parameters, and indeed grammatical principles (e.g. Chomsky, 1981; Lightfoot, 1992) is broadly supported. Insofar as such information is incorporated as absolute principles then, given the coevolutionary scenario developed here, this has the effect of forcing languages to adapt to these evolving constraints. However, insofar as such information takes the form of defeasible biases or preferences during learning, linguistic variants will be more or less learnable depending on their compatibility with such biases. Therefore, we would expect to see peripheral constructions and typologically rarer grammatical systems which violate some of them. Similarly, the account predicts that assimilation will be partial as a result of linguistic change during the period of adaptation. Bickerton's (e.g. 1984) Bioprogram Hypothesis, receives qualified support, if it is interpreted as the claim that the LAD incorporates specific default parameters specifying a minimal default SVO right-branching grammar, because this will only be the outcome of genetic assimilation if the environment of adaptation for the LAD was dominated by a language, or languages, with grammars (mostly) consistent with such defaults.³²

The evolutionary simulation model demonstrates that embedding a generative

³²The ranking of languages in terms of the WML parsability metric, in fact, does predict that a right-branching SVO grammar might have been favoured at an early stage in grammatical development when complex multiword NPs and subordinate clauses had developed, but before rules of reordering had emerged, such as extraposition, scrambling, v1 and v2. SVO and some variants with a single left-branching construction are clustered at the top of this ranking, discounting languages such as SOVv2 and VSOv1 and variants which involve these more complex reordering mechanisms (which might plausibly have emerged as a later response to the apparently slightly less optimal canonical SOV and VSO orders). However, the ranking which is used in the simulation relies on taking the mean WML for the exemplar sentence types for each language. This makes the implicit assumption that the (probabilistic) distribution of sentence types in interactions is unbiased. This is true in the simulation but is manifestly not true of actual language use. Hawkins (1994:180f), for instance, presents evidence that sentence types which severely tax parsing are used rarely by speakers. Therefore, the predictions made by the WML ranking must be treated with caution when assessing the 'optimality' of actual languages.

model of the LAD in a changing population of LAGts leads naturally to an account of language in which idiolects are well-defined stringsets, but languages are (complex) adaptive systems. Linguistic selection is primarily a consequence of properties of the LAD, and slight changes in the model of the LAD may create markedly different selection pressures. The model of working memory load incorporated into the GCG parser predicts that relative ease of parsability will be a factor in linguistic selection under almost any assumptions about the impact of parsability on language learning or use. The experiments on linguistic selection reported here underline the need for natural selection for communicative success to maintain language in a population capable of biological evolution. They, therefore, cast doubt on claims made, in the context of simulations in which no biological evolution occurred (e.g. Kirby, 1996; Steels, 1998), that linguistic selection alone is sufficient to explain the emergence and subsequent evolution of language. Nevertheless, there are inadequacies in the current simulation model which should be addressed; for example, the model of expressiveness and its effect on language development is too crude and incapable of supporting an account of the gradual accumulation of grammatical constructions. Furthermore, the results reported here are relative to the specific choices made in modelling the LAD.

Finally, it is important to consider whether *any* simulation model allowing evolution of both LAGts and grammatical systems and conferring selective advantage to communicating LAGts would not show (some) genetic assimilation. Mayley (1996) demonstrates via a model and experiments that for genetic assimilation to occur there must be correlation between neighbouring phenotypes, attainable through lifetime adaptations, and their corresponding genotypes. In terms of the current simulation model, there is considerable correlation between steps of the acquisition procedure to converge on a specific grammatical system (i.e. parameter updates) and moves in genotype space representing biological evolution (i.e. changes in LAGts' initial p-settings) which reduce the number of learning steps. If, on the other hand, any small improvement in the acquisition procedure with respect to any target class of grammars required many changes at genotypic level (or vice-versa), then genetic assimilation would be unlikely to occur, even with selective pressure to learn language more efficiently.

Our current lack of knowledge of the neural basis of UG and parameter setting and of its genetic basis does not allow a definitive answer to the question of correlation. However, whilst the operations involved are no doubt very different from their representation in the simulation model, if we assume that learning applies to further specify a partial grammatical representation which itself is specified genetically, it is difficult to see how or why a highly uncorrelated genetic encoding of the neural representation might evolve. Nevertheless, the question does highlight the conditional nature of the conclusions which can be drawn from the results of any such (simulation) model. Not only the assumptions behind the model but also the many contingent, accidental or chance factors in the actual, but prehistoric, evolution of language and its users may undermine the results. Nevertheless, models of this type have heuristic value in guiding us towards hypotheses which can then be further tested by other means; for example, claims about the effect of working memory on parsing are testable, in principle, via psycholinguistic experimentation or typological investigations, even though claims about the prehistoric development of language are not. Furthermore, such models can be used to evaluate evolutionary theorizing about language which does not utilize a simulation methodology and to expose implicit and, perhaps, incorrect inferences or assumptions in such theorizing; for example, in Deacon's (1997:329) arguments from rapid relative linguistic change to the implausibility of genetic assimilation of grammatical knowledge.

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